Assignment #8: due Tuesday, Dec. 11

Theoretical Astrophysics

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1. Magnetic Braking of an Alligned Rotor

Consider a uniform gaseous disk of density $\rho_{\rm cl}$ and half-thickness Z rotating rigidly with an initial angular velocity Ω_0 . Furthermore assume the disk is threaded with a magnetic field \vec{B} of strength B_0 , initially uniform and parallel to the rotation axis. The magnetic field links the disk with the external medium of density $\rho_{\rm ext}$ which is initially at rest. Assume axisymmetry and use cylindrical coordinates (R, φ, z) for the calculations.

- (a) Derive the evolution equations for the toroidal magnetic field B_{φ} and the angular velocity Ω (where $v_{\varphi} = R \Omega$) outside of the disk, i.e. |z| > Z, assuming that the radial velocity v_r and the poloidal velocity v_z are negligible small (compared to the Alfvén velocity).
- (b) Show that the evolution of the external medium can be expressed by the wave equation

$$\frac{\partial^2 \Omega}{\partial t^2} = v_{\rm A,ext}^2 \frac{\partial^2 \Omega}{\partial z^2} \tag{1}$$

where $v_{A,ext} = B_0 / \sqrt{4\pi \rho_{ext}}$ is the Alfvén velocity in this medium.

(c) Derive the evolution equation of the angular velocity at the surface of the disk, i.e. |z| = Z, using the torque per unit area, $N = R B_0 B_{\varphi}/4\pi$, which the magnetic field exerts on the surface of the disk. Result:

$$\frac{\partial^2 \Omega_{\rm cl}}{\partial t^2} = \frac{1}{Z} \left. \frac{\rho_{\rm ext}}{\rho_{\rm cl}} \, v_{\rm A,ext}^2 \left. \frac{\partial \Omega}{\partial z} \right|_{|z|=Z} \tag{2}$$

(d) Combine equations (1) and (2) to calculate the spin-down time of the disk. [Use the solution of equation (1) at the disk surface |z| = Z.]

2. A Simple Approach to Magnetorotational Instability 35 pt

The simplest system that displays the magnetorotational instability is an axissymmetric differentially rotating gaseous disk in the presence of a weak vertical magnetic field, i.e. $\vec{B}_0 = B_z \vec{e}_z$. We assume the disk is initially homogeneous with density ρ_0 and has no radial or vertical motions, i.e. $\vec{v}_0 = v_{\varphi} \vec{e}_{\varphi}$. In the following

40 pt

we consider a fluid element that is displaced from its appropriate circular orbit by a small distance $\vec{x} = x_R \vec{e}_R + x_{\varphi} \vec{e}_{\varphi}$, where the displacement follows a vertical oscillation $\propto \exp(ikz)$. We neglect the effects of viscosity and study time evolution of the system with perturbations induced as described above. As in the previous assignment we use a cylindrical coordinate system.

(a) Derive the equations of magneto-hydrodynamics for this system to linear order for the quantities $\delta \rho$, δP , $\delta \vec{u}$, and $\delta \vec{B}$, which are perturbed density, pressure, velocity and magnetic field, respectively. Consider the velocity \vec{u} which denotes the deviation of the true fluid velocity \vec{v} at any location from the azimuthal circular velocity $R\Omega(R)\vec{e}_{\varphi}$,

$$u_R = v_R , \qquad u_\varphi = v_\varphi - R\Omega(R) , \qquad u_z = v_z , \qquad (3)$$

and where $\Omega(R)$ is the circular velocity at radius R. The result is,

$$-\omega \frac{\delta \rho}{\rho} + k \delta u_z = 0 , \qquad (4)$$

$$-i\omega\delta u_R - 2\Omega\delta u_{\varphi} - i\frac{kB_z}{4\pi\rho}\delta B_R = 0 , \qquad (5)$$

$$-i\omega\delta u_{\varphi} + \frac{\kappa^2}{2\Omega}\delta u_R - i\frac{kB_z}{4\pi\rho}\delta B_{\varphi} = 0 , \qquad (6)$$

$$-\omega\delta u_z + k\frac{\delta P}{\rho} = 0 , \qquad (7)$$

$$-\omega\delta B_R = kB_z\delta u_R , \qquad (8)$$

$$-i\omega\delta B_{\varphi} = ikB_z\delta u_{\varphi} , \qquad (9)$$

$$\delta B_z = 0 , \qquad (10)$$

where κ is the epicyclic frequency,

$$\kappa^2 = \frac{1}{R^3} \frac{d(R^4 \Omega^2)}{dR} , \qquad (11)$$

which usually has values in the range $\Omega \leq \kappa \leq 2\Omega$. To close this set of equations we take the usual equation of state,

$$\frac{\delta P}{P} = \gamma \frac{\delta \rho}{\rho} \ . \tag{12}$$

- (b) Using equations (4) to (12) relate $\delta \vec{B}$ to the displacement vector \vec{x} . (Recall that $d\vec{x}/dt = \vec{u}$ and $d/dt \rightarrow i\omega$ in Fourier space.)
- (c) We now can substitute the magnetic field terms in the equations of motion. Show that these equations describe the R and φ component of the displacement vector as a set of coupled damped oscillators. Use these equations to find the criterion for instability. Discuss your result.