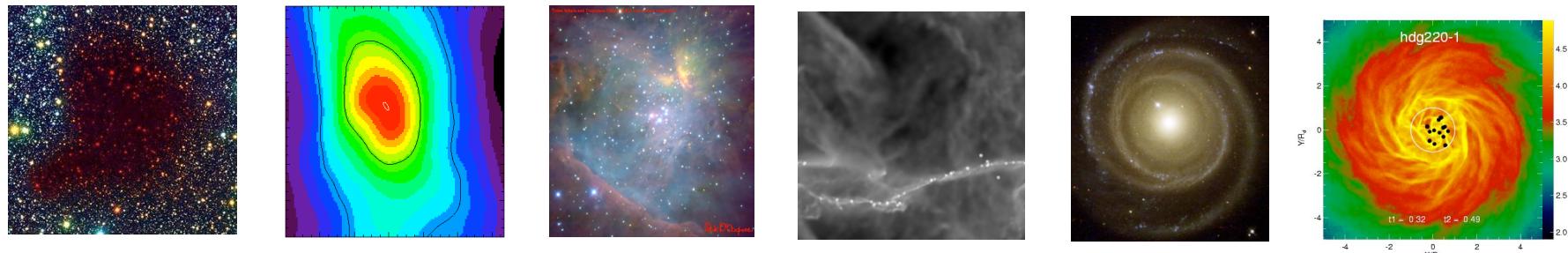


ISM dynamics: theoretical considerations



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ISM dynamics: theoretical considerations

- o phenomenology
- o derivation of the hydrodynamic equations
- o virial theorem
- o Jeans criterion: critical mass for gravitational collapse
- o Bonnor-Ebert spheres: pressure-bounded gas sphere in hydrostatic equilibrium



Star formation in “typical” spiral:

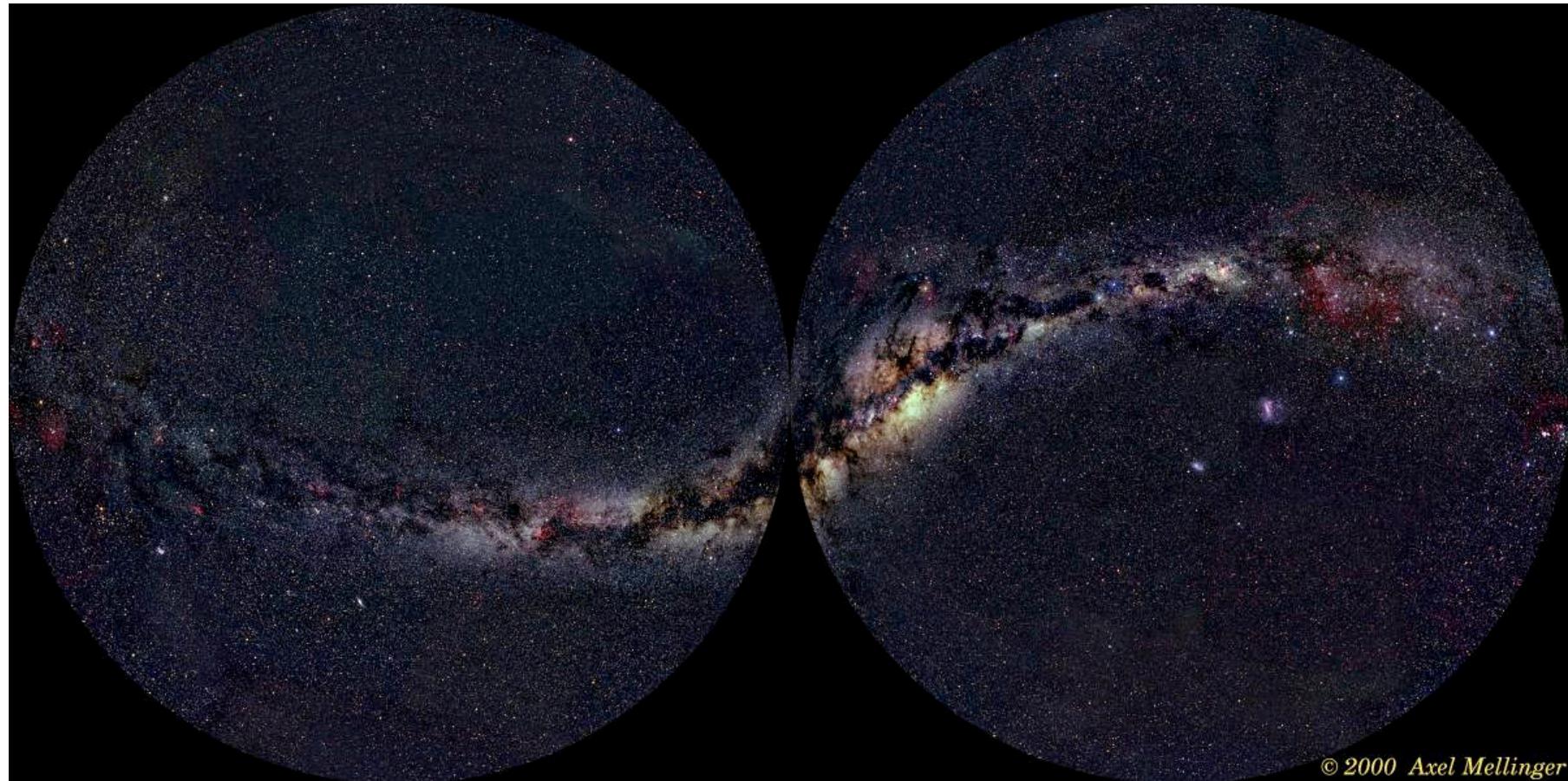


(from the Hubble Heritage Team)

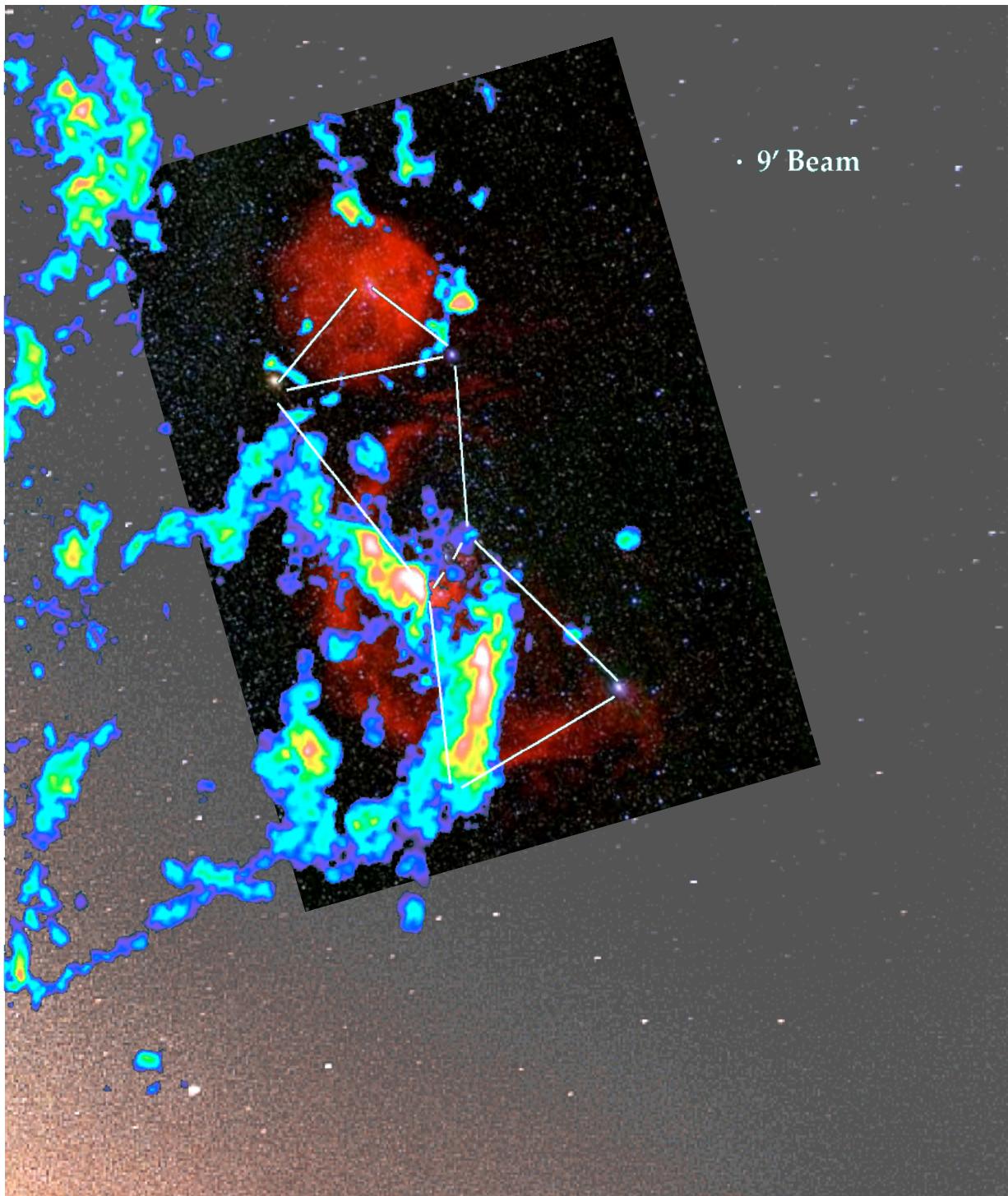
NGC4622

- Star formation *always* is associated with *clouds of gas and dust*.
- Star formation is essentially a *local phenomenon* (on ~pc scale)
- **HOW** is star formation *influenced by global properties* of the galaxy?

Star forming clouds in the Milky Way



© 2000 Axel Mellinger

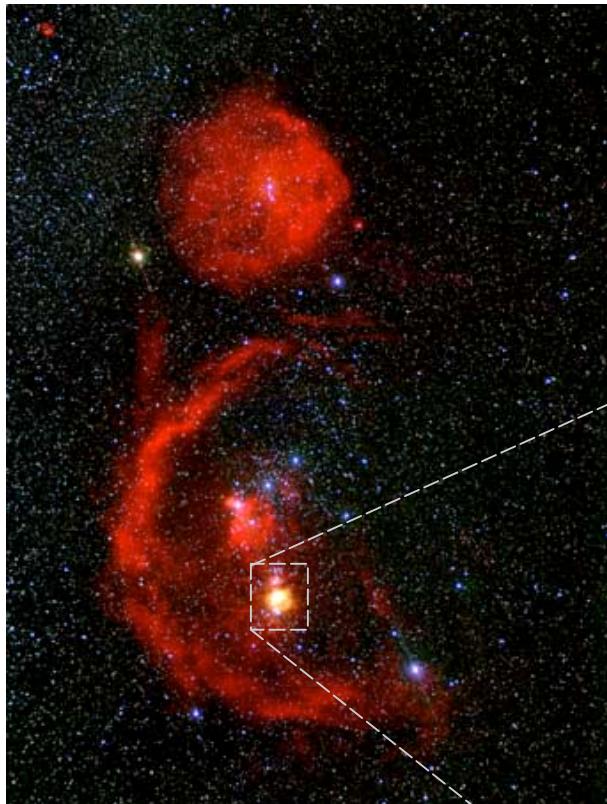


Star formation in Orion

We see

- *stars* (in optical light)
- *atomic hydrogen* (in H α -- red)
- *molecular hydrogen H_2* (radio -- color coded)

Local star forming region: The Trapezium Cluster in Orion



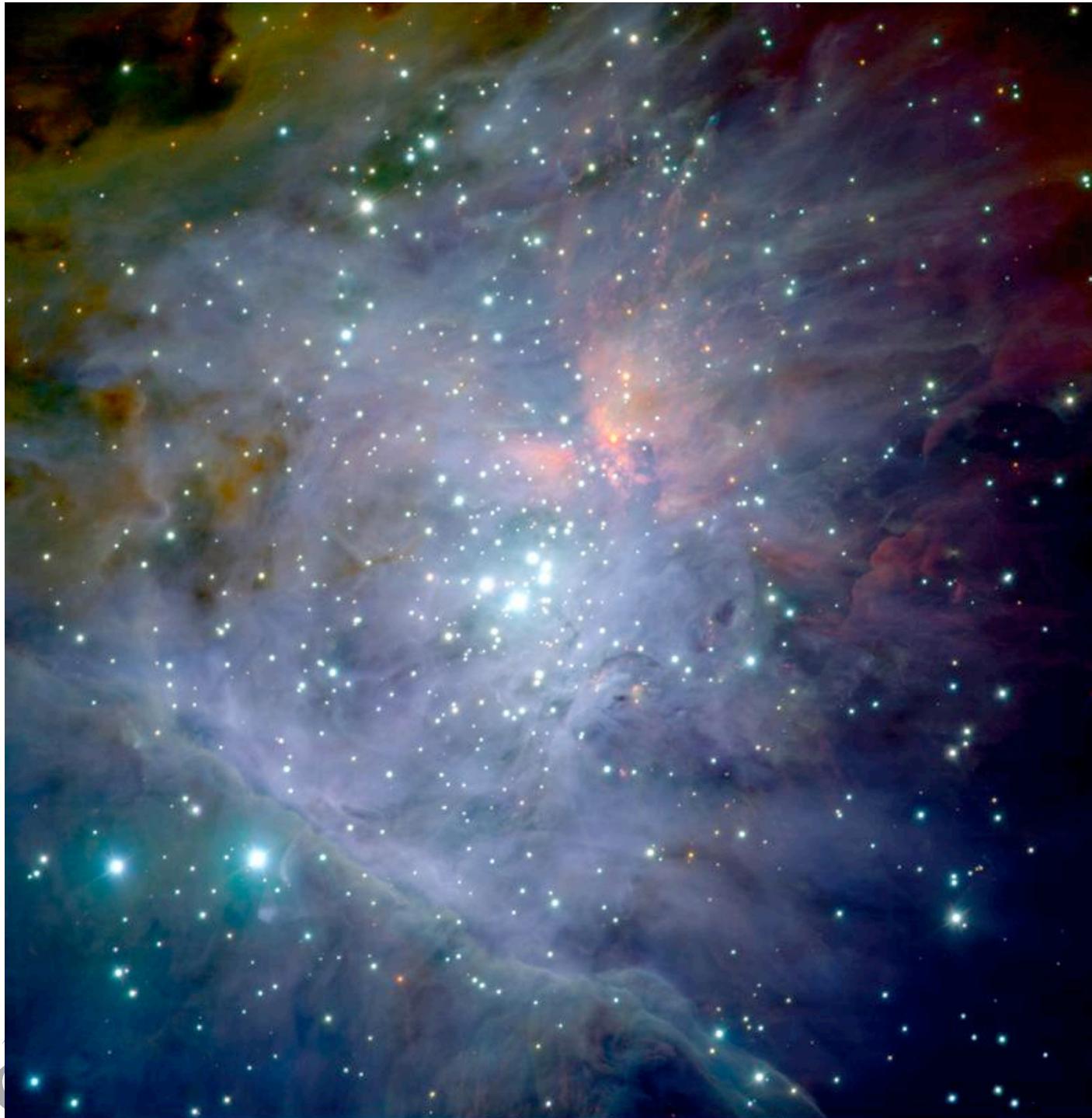
Orion molecular cloud

The Orion molecular cloud is the birth- place of several young embedded star clusters.

The Trapezium cluster is only visible in the IR and contains about 2000 newly born stars.



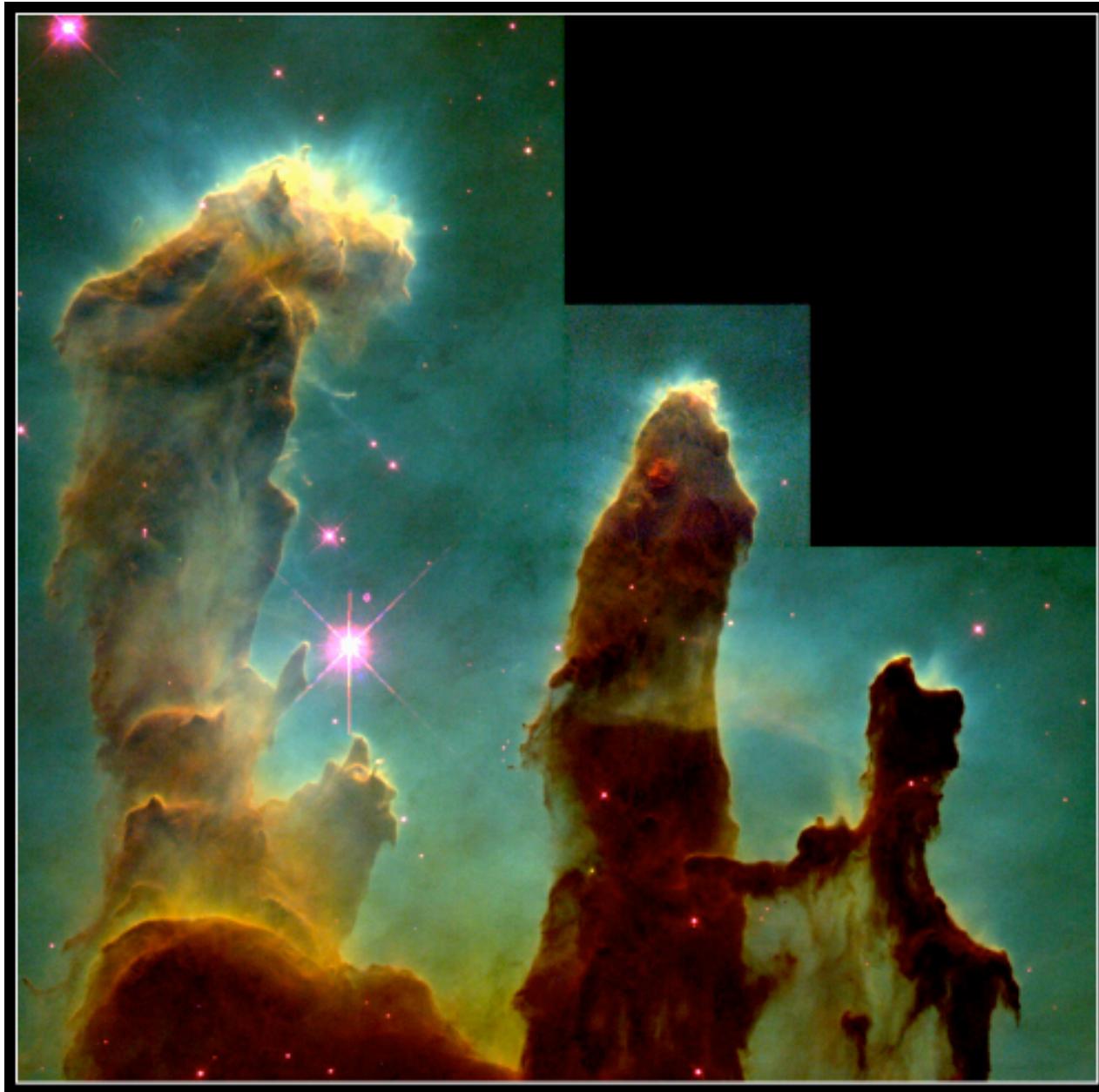
Trapezium
cluster



Trapezium Cluster (detail)

- stars form in **clusters**
- stars form in **molecular clouds**
- (proto)stellar **feedback** is important

(color composite J,H,K
by M. McCaughean,
VLT, Paranal, Chile)



HST Aufnahme

Pillars of God (in Eagle Nebula): Formation of small groups of young stars in the tips of the columns of gas and dust

Infrared
observation



IR observation with ESO-VLT



Pillars of God (in Eagle Nebula): Formation of small groups of young stars in the tips of the columns of gas and dust

IR observation with ESO-VLT



Head of Column No.2 in Eagle Nebula (IR-View)
(VLT ANTU + ISAAC)

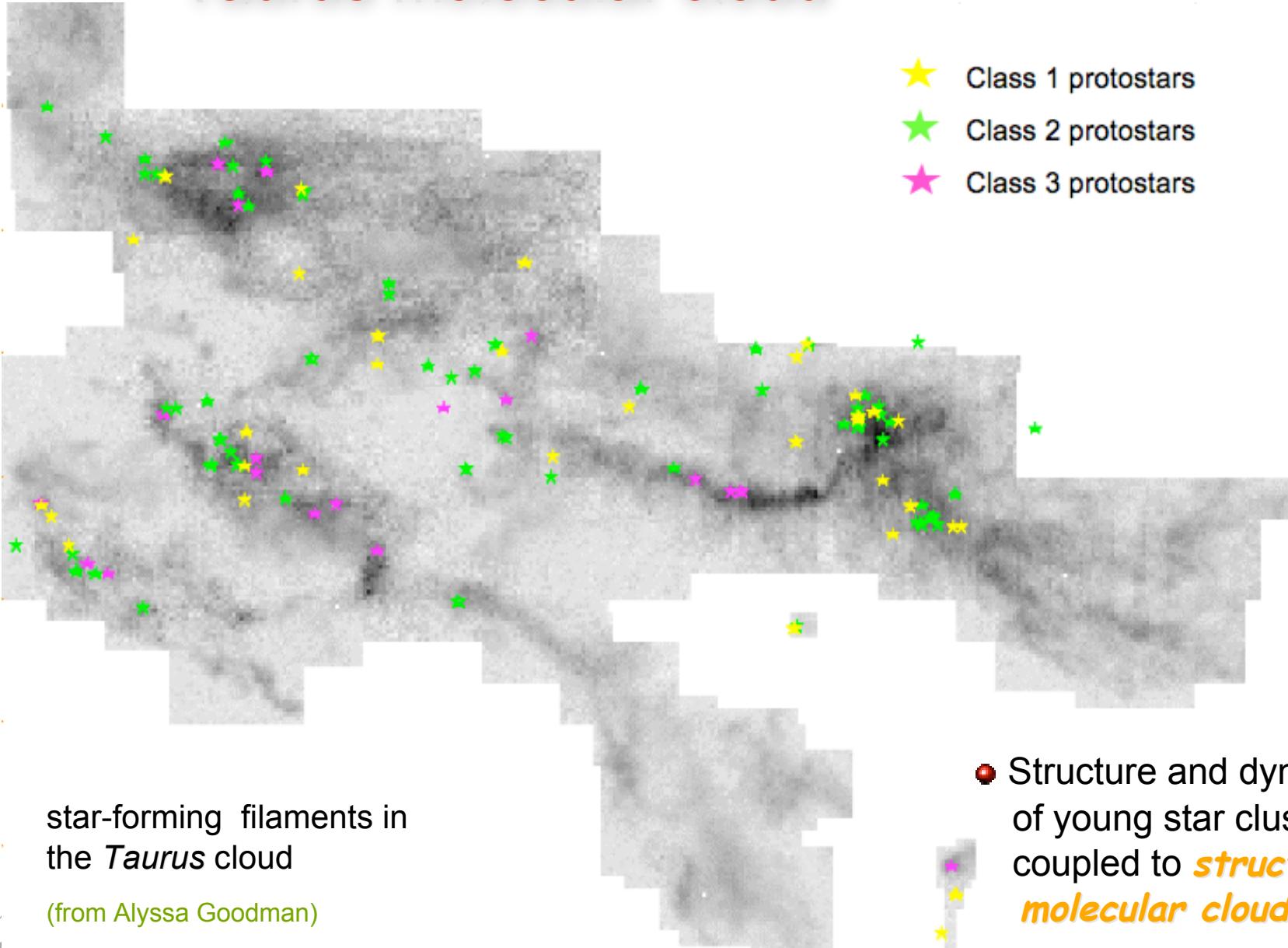
ESO PR Photo 370/01 (30 December 2001)

© European Southern Observatory



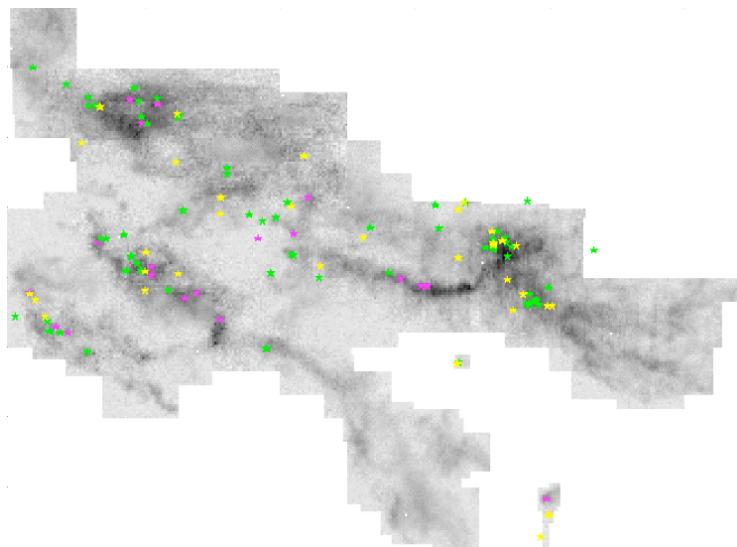
Pillars of God (in Eagle Nebula): Formation of small groups of young stars in the tips of the columns of gas and dust

Taurus molecular cloud



- Structure and dynamics of young star clusters is coupled to *structure of molecular cloud*

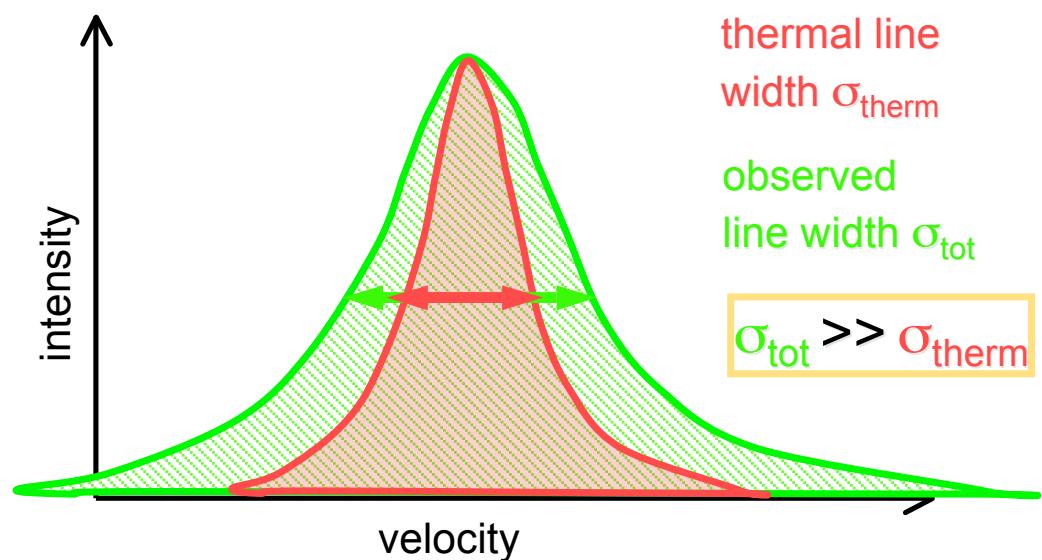
Taurus molecular cloud

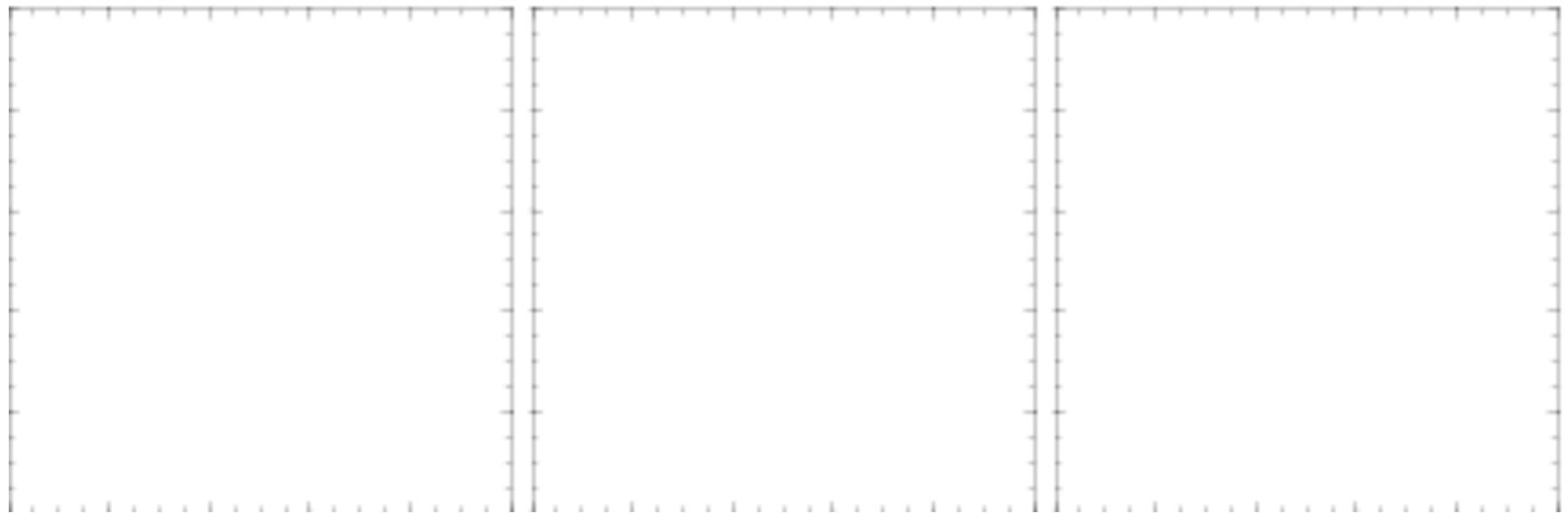


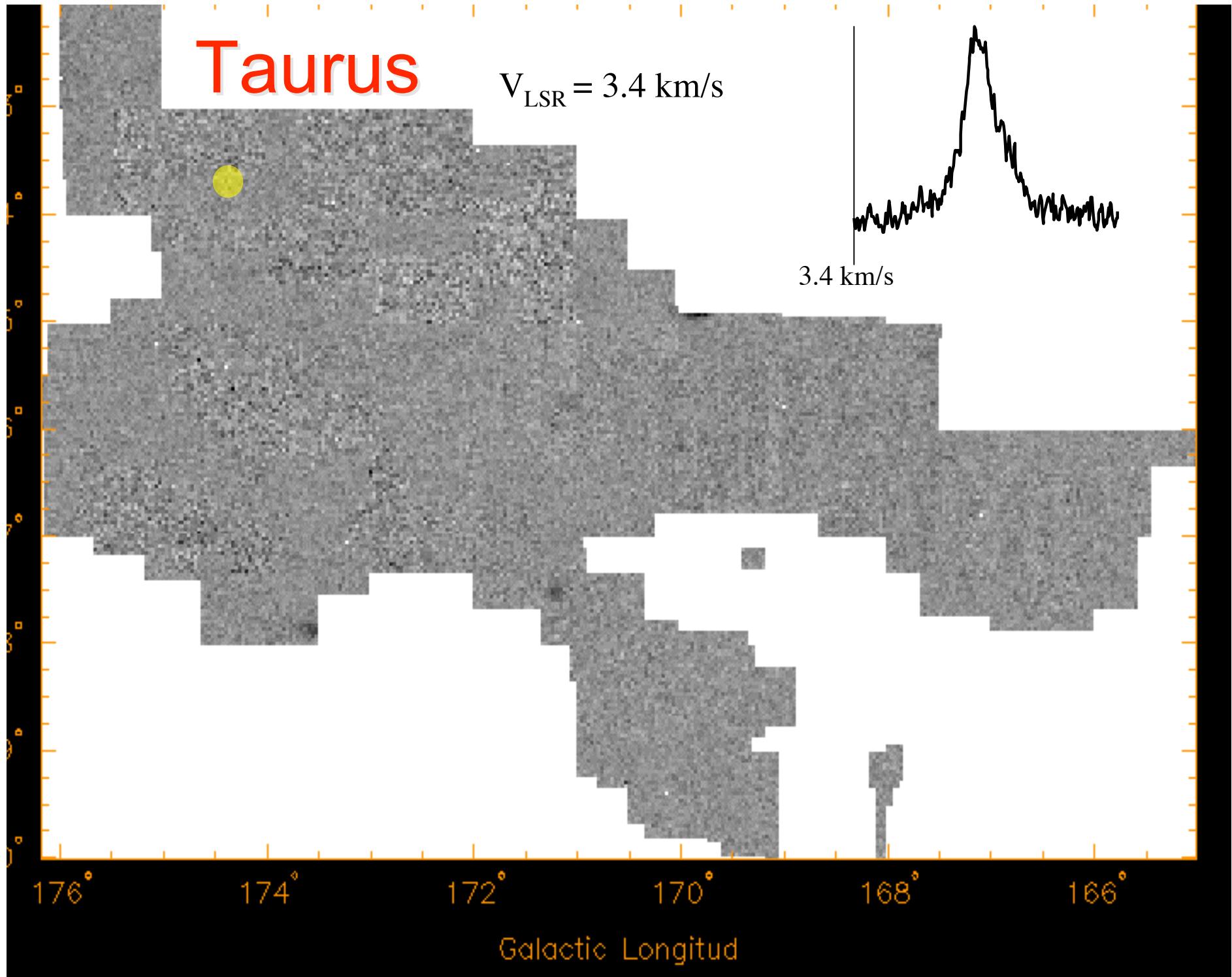
Star-forming filaments in *Taurus* cloud

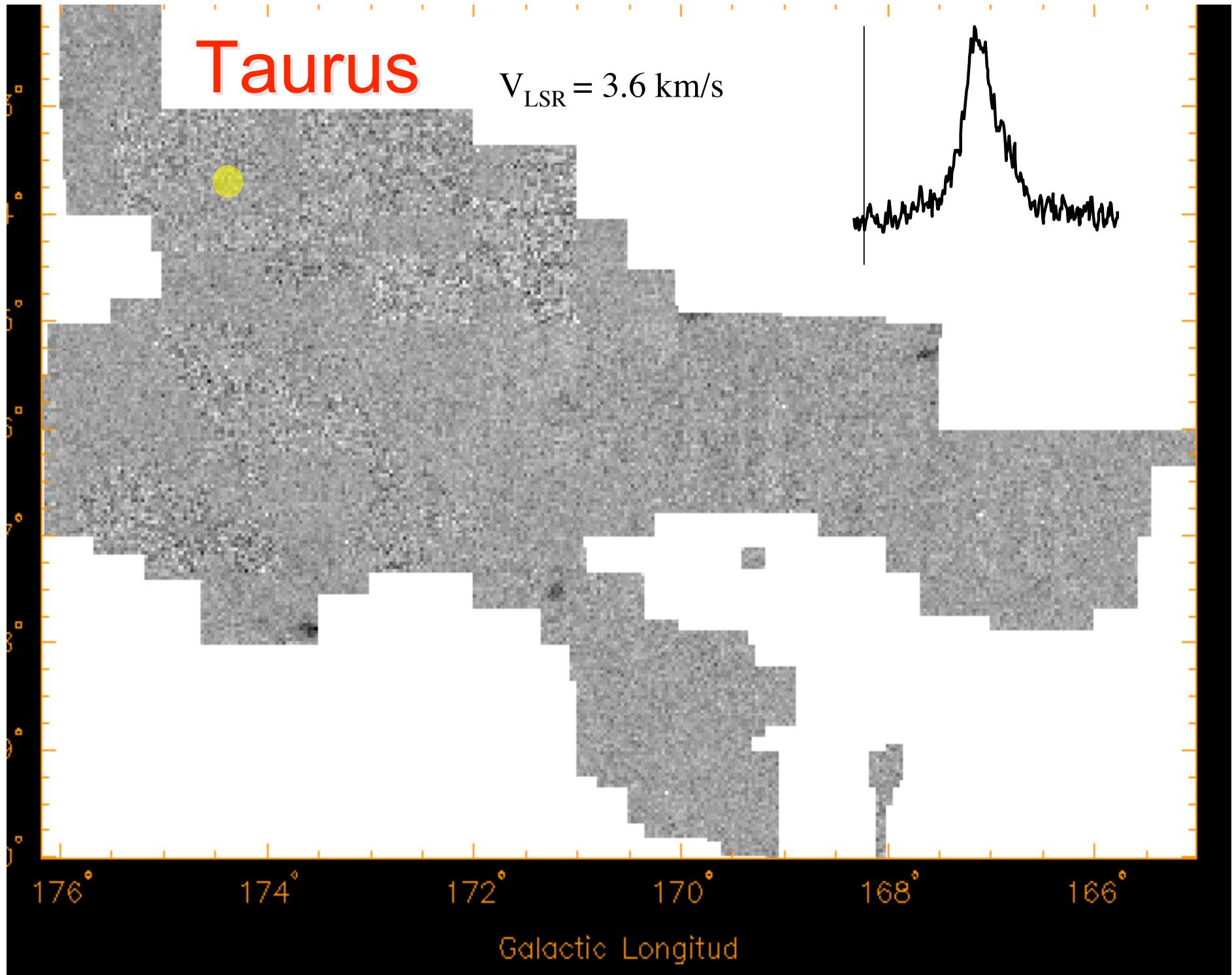
(from Hartmann 2002)

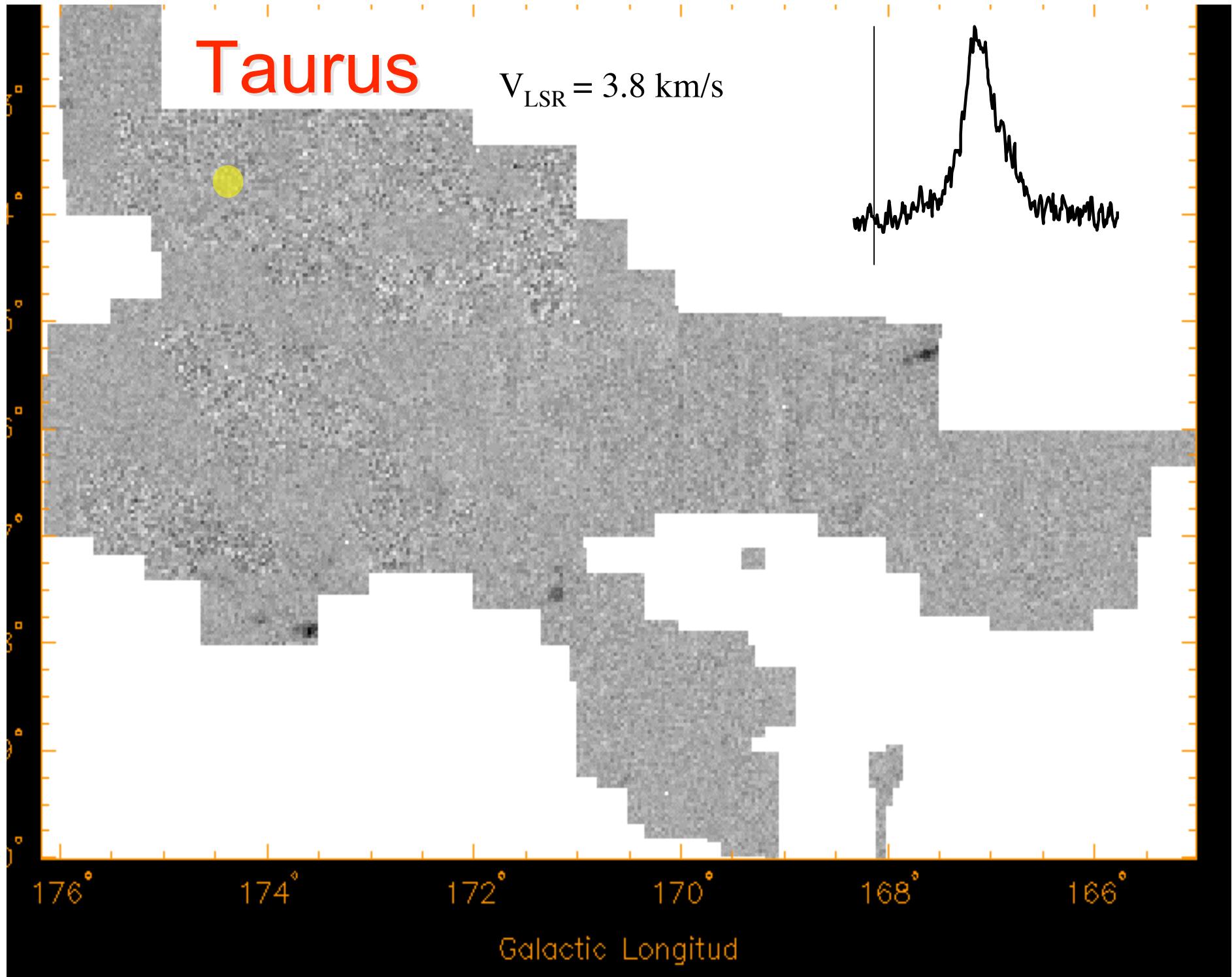
- Structure and dynamics of young star clusters is coupled to *structure of molecular cloud*

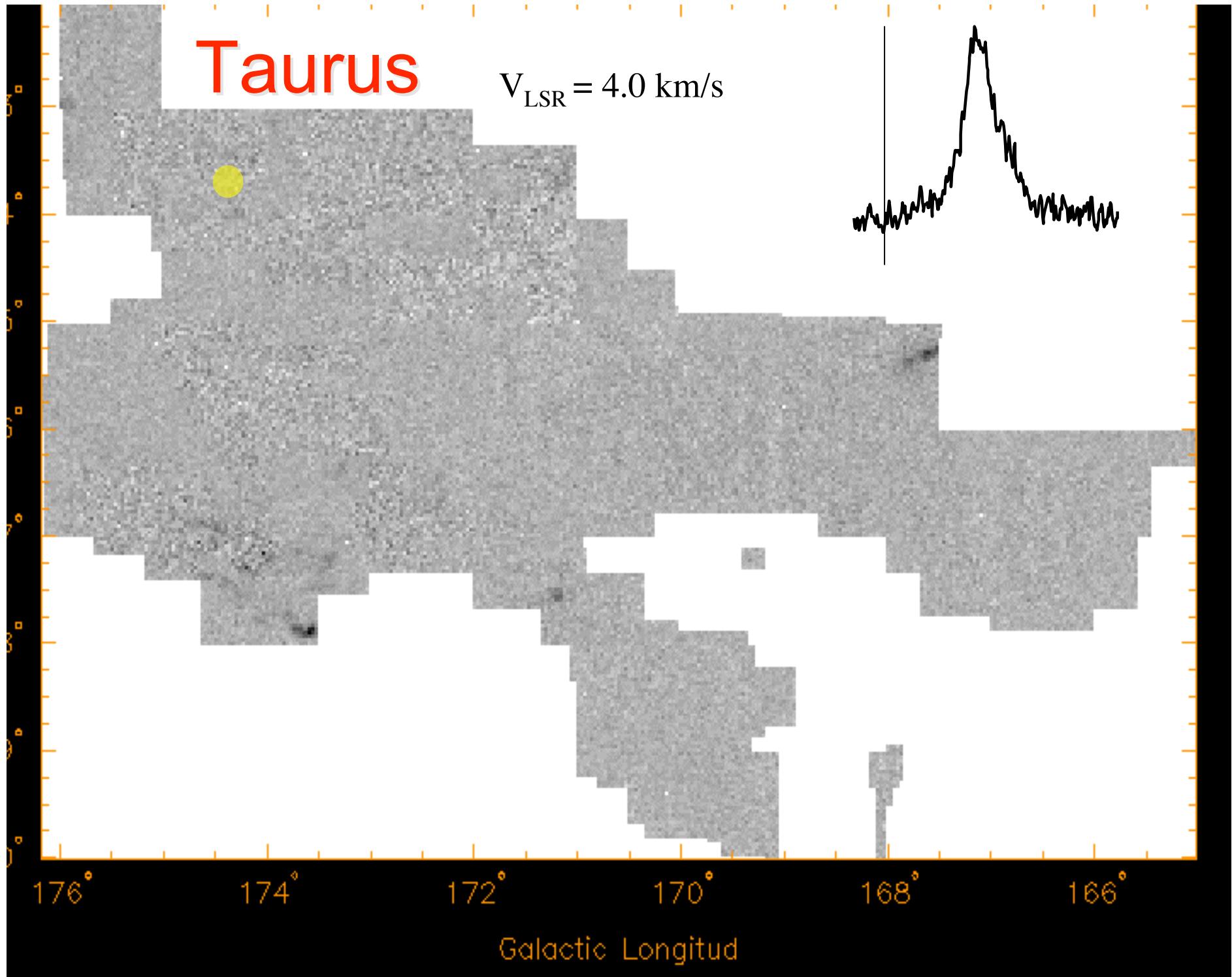


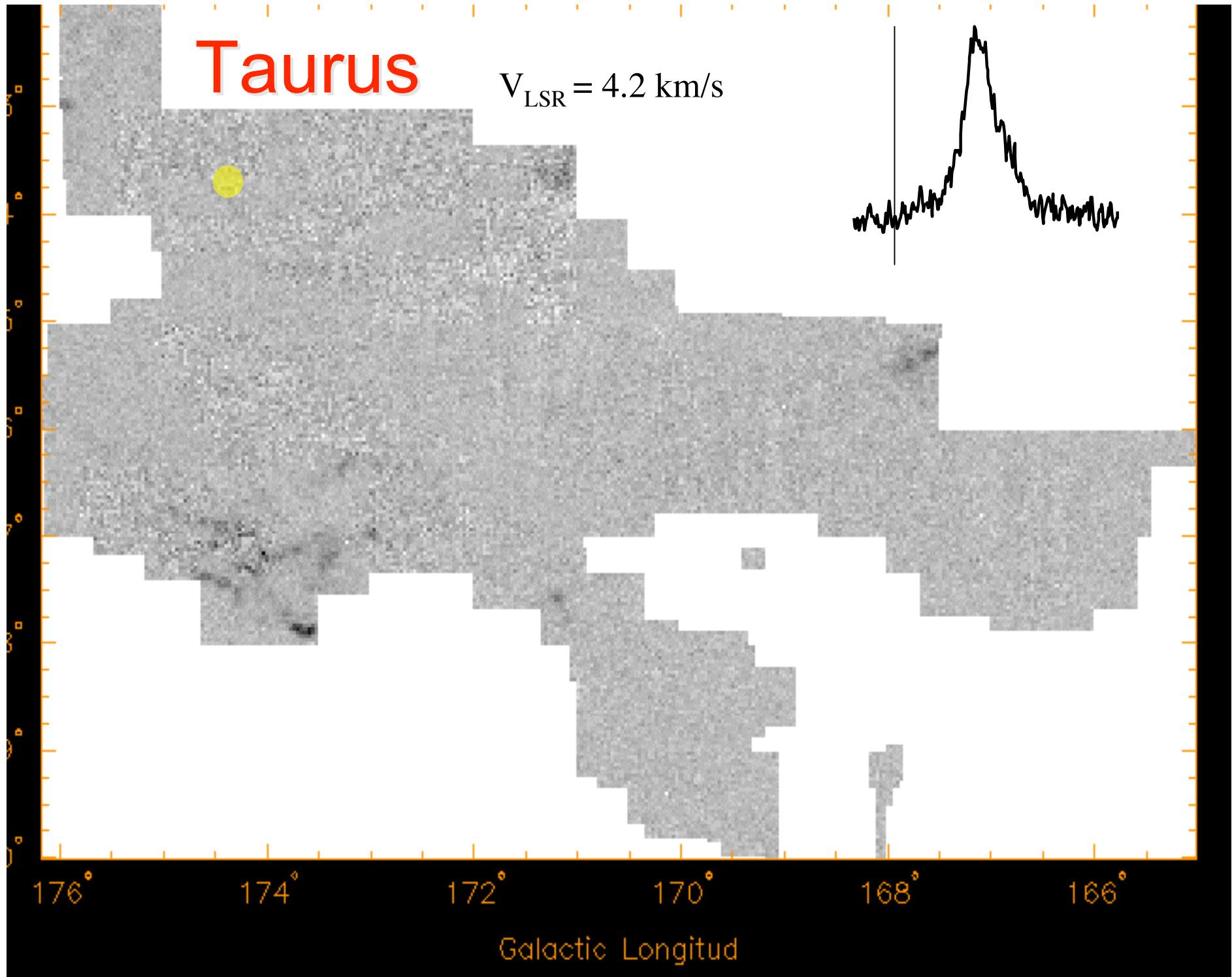


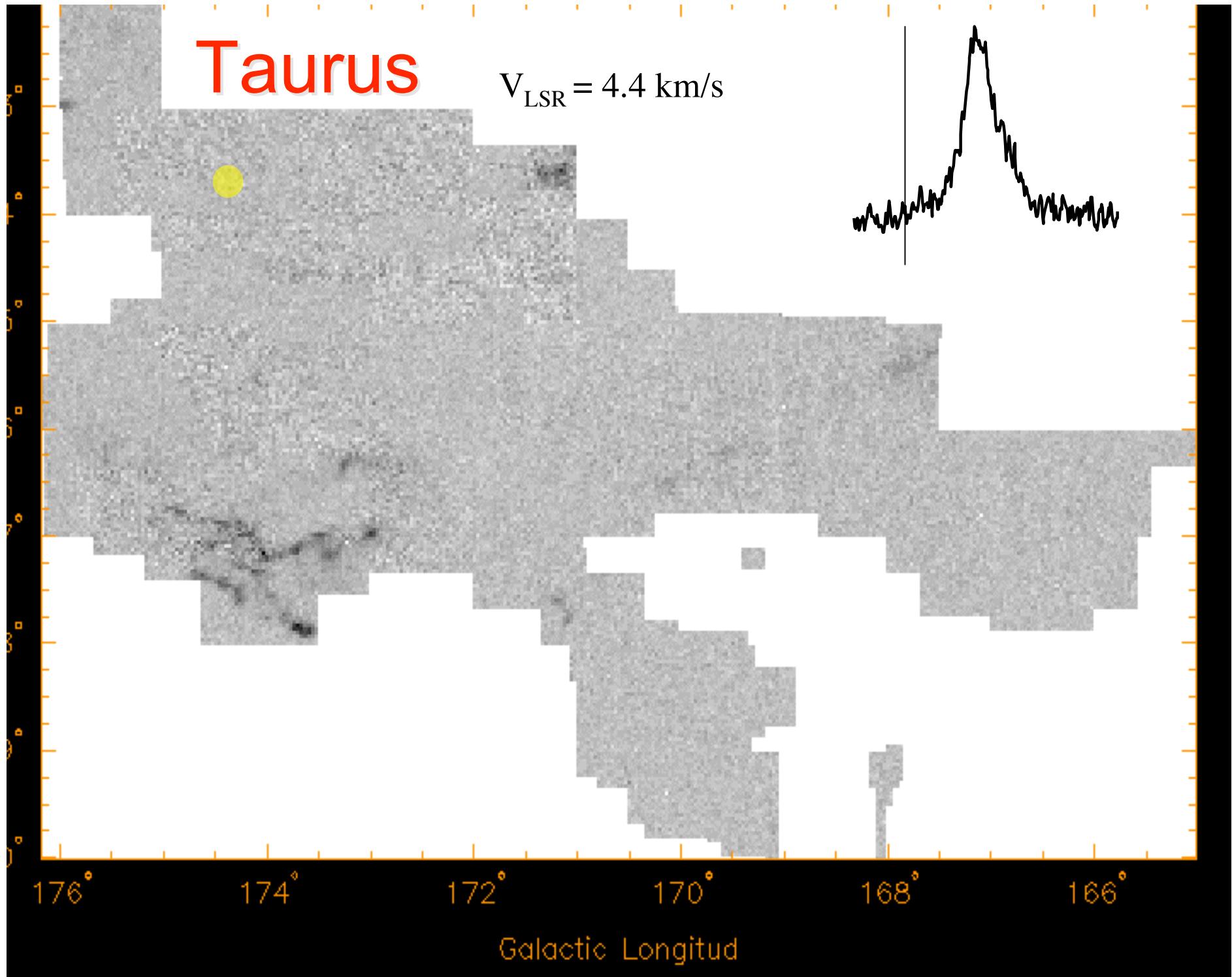


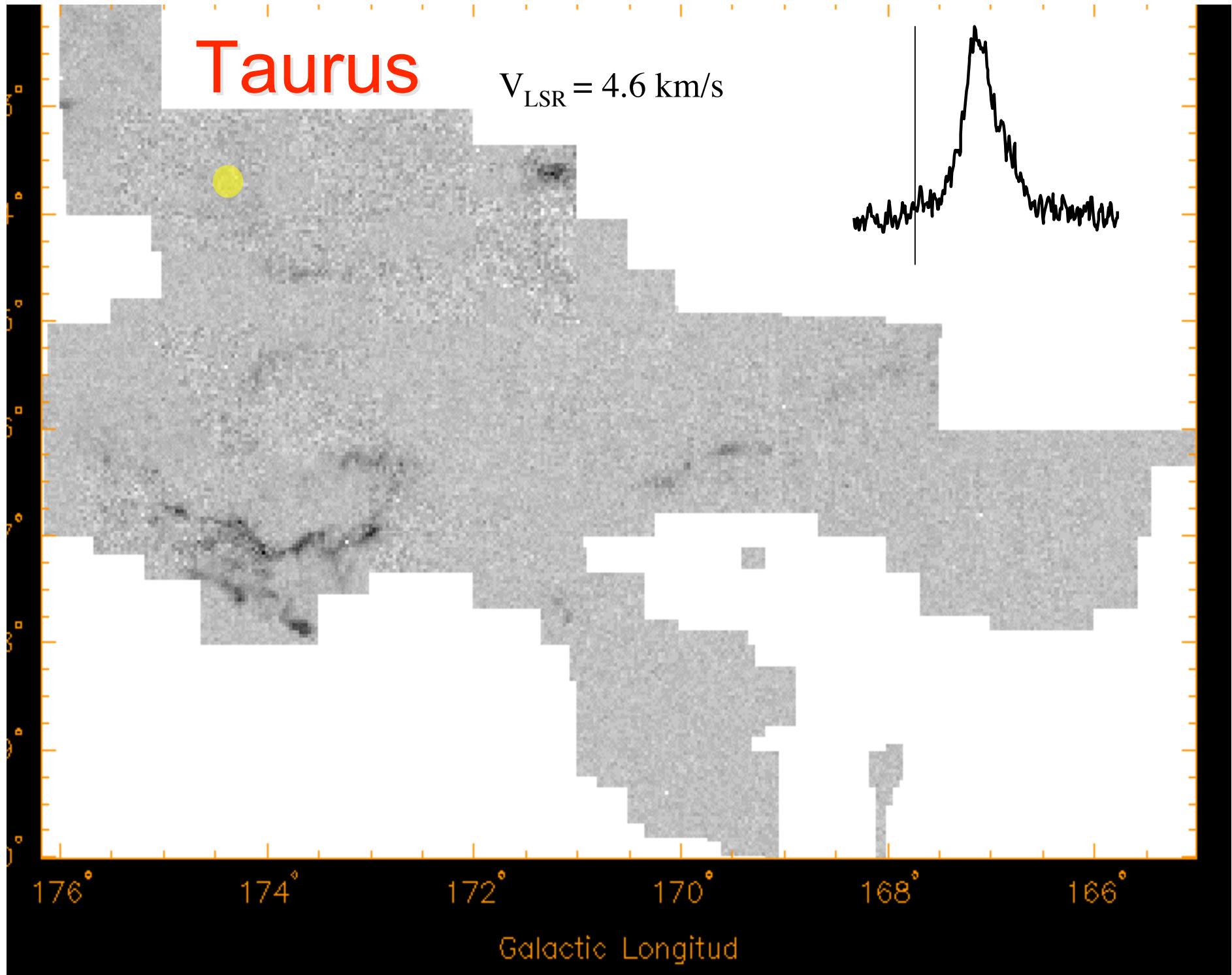


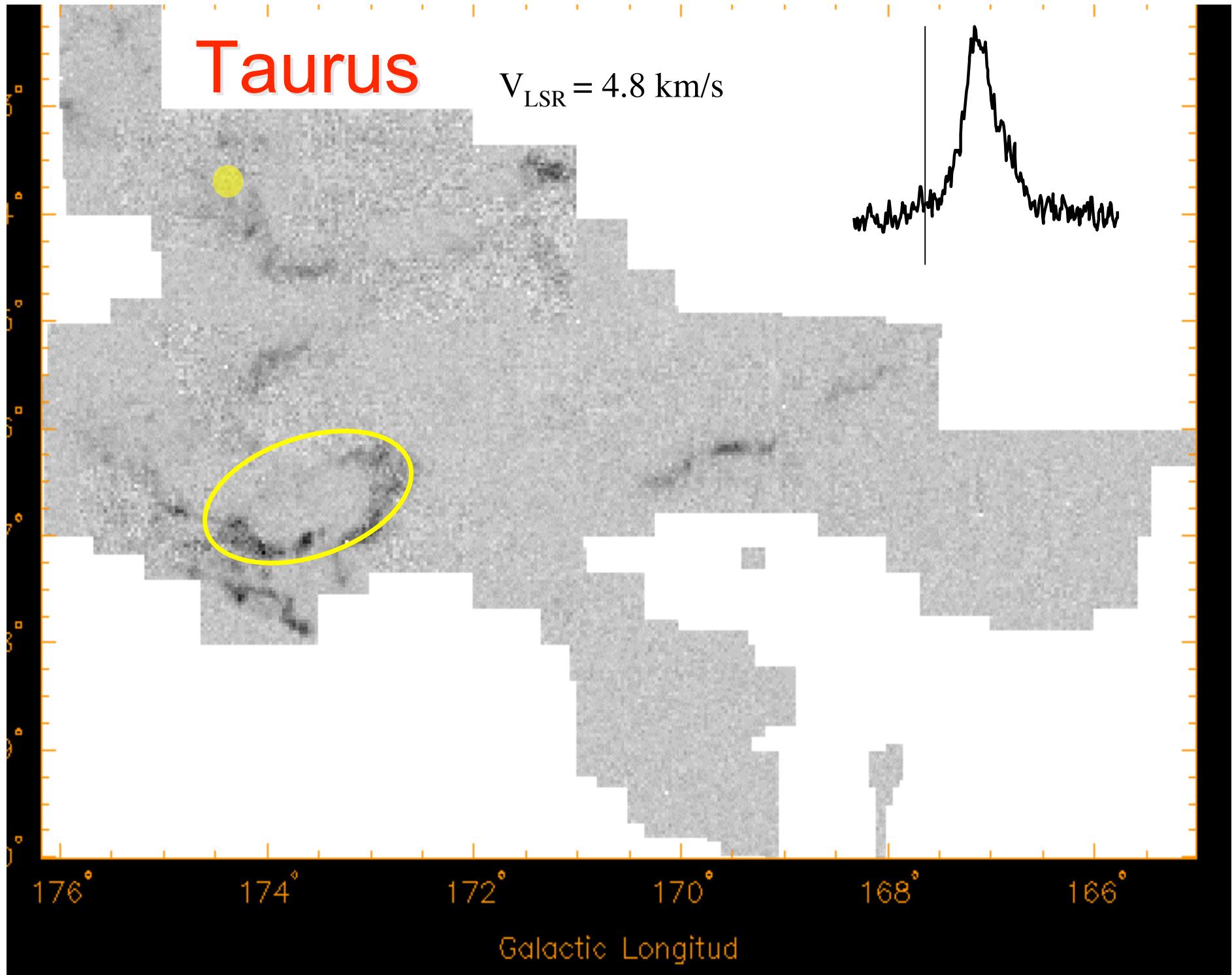


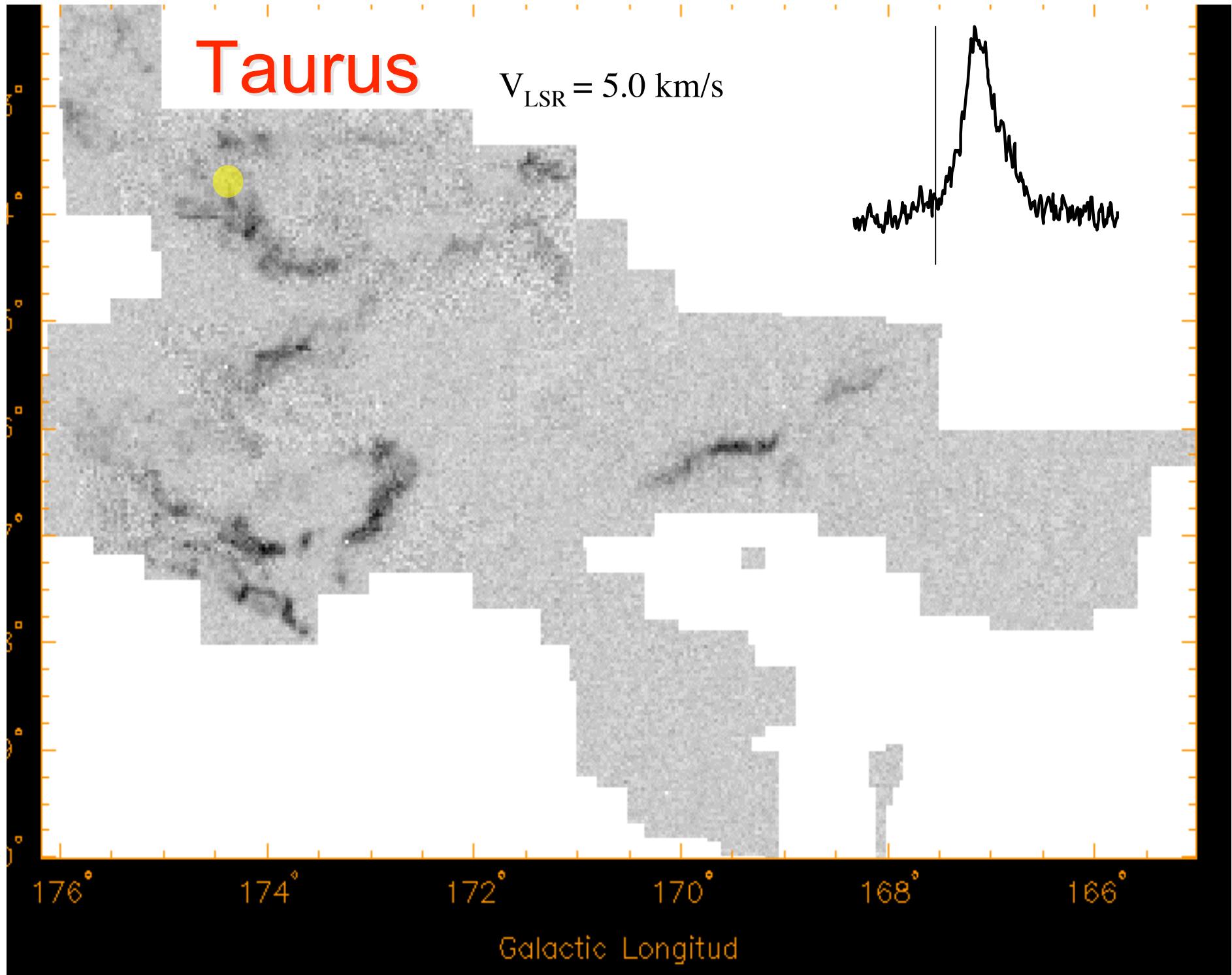


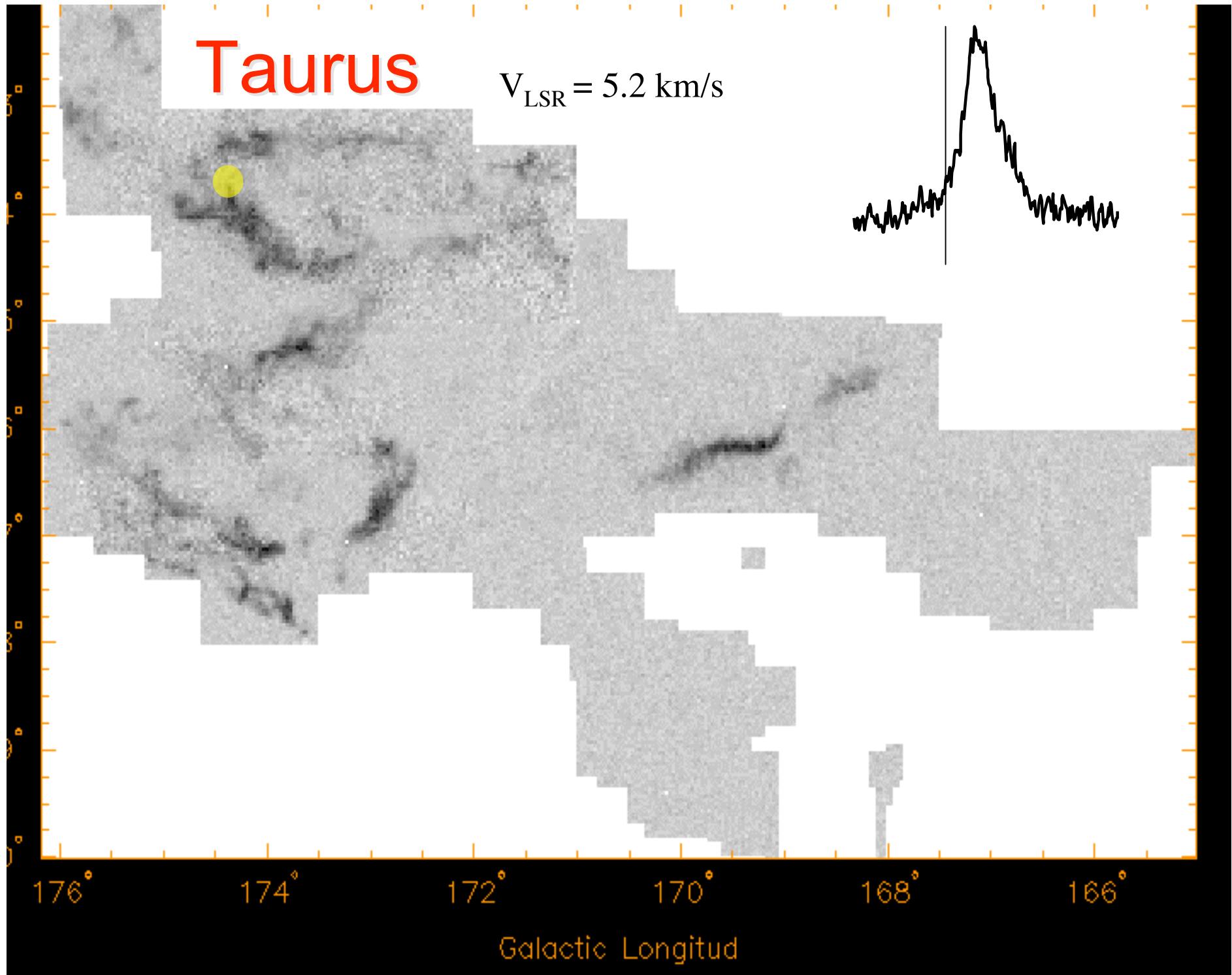


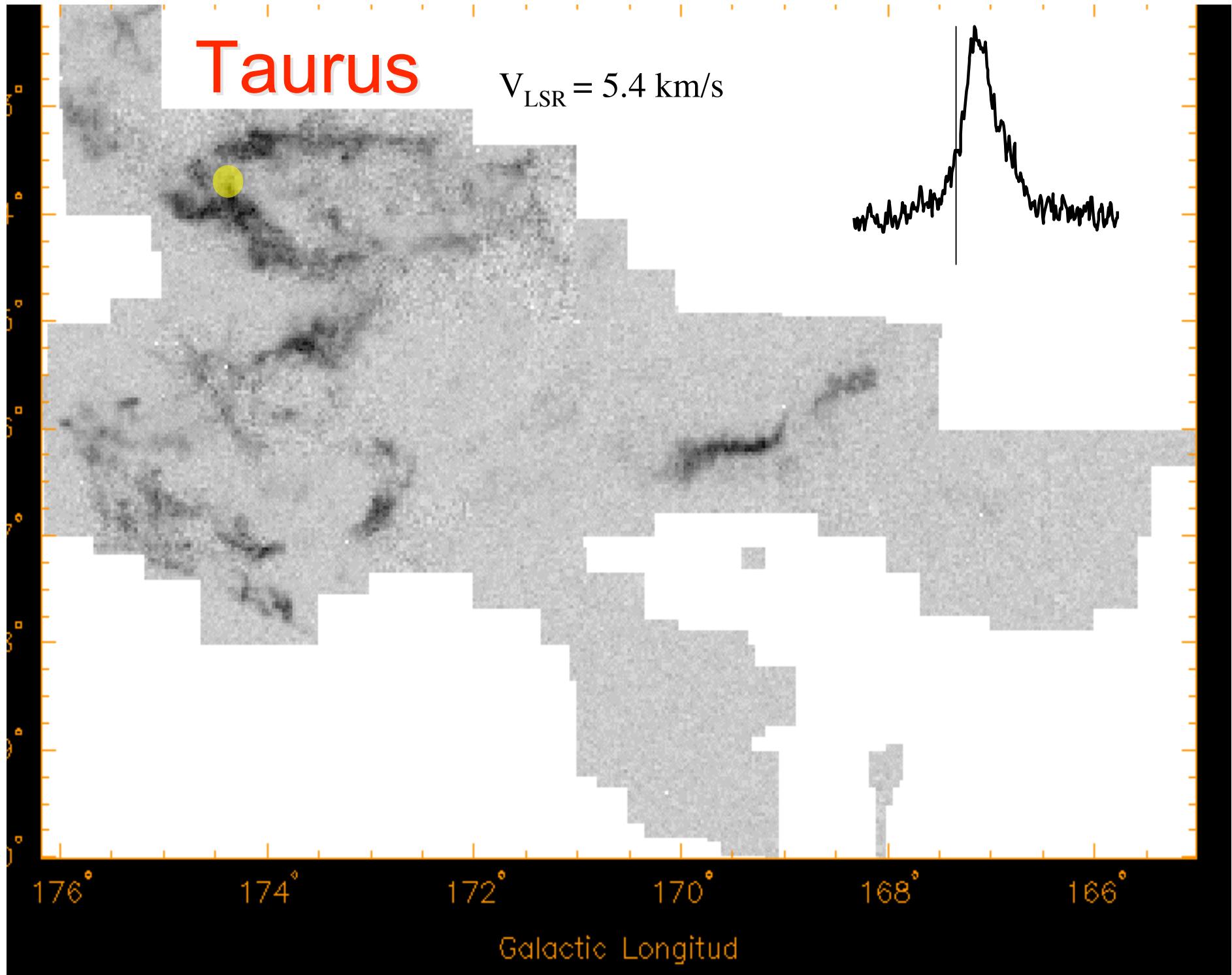


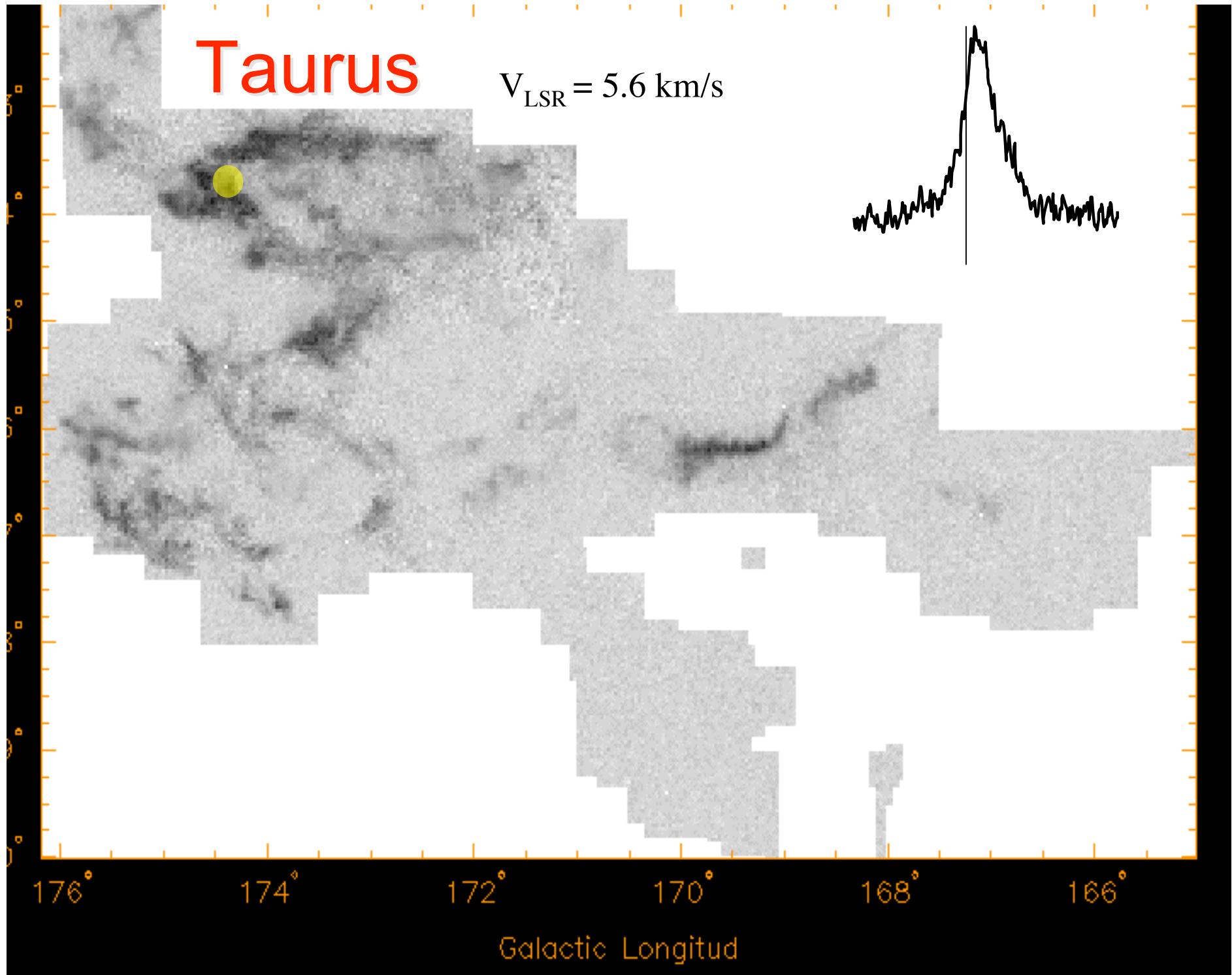


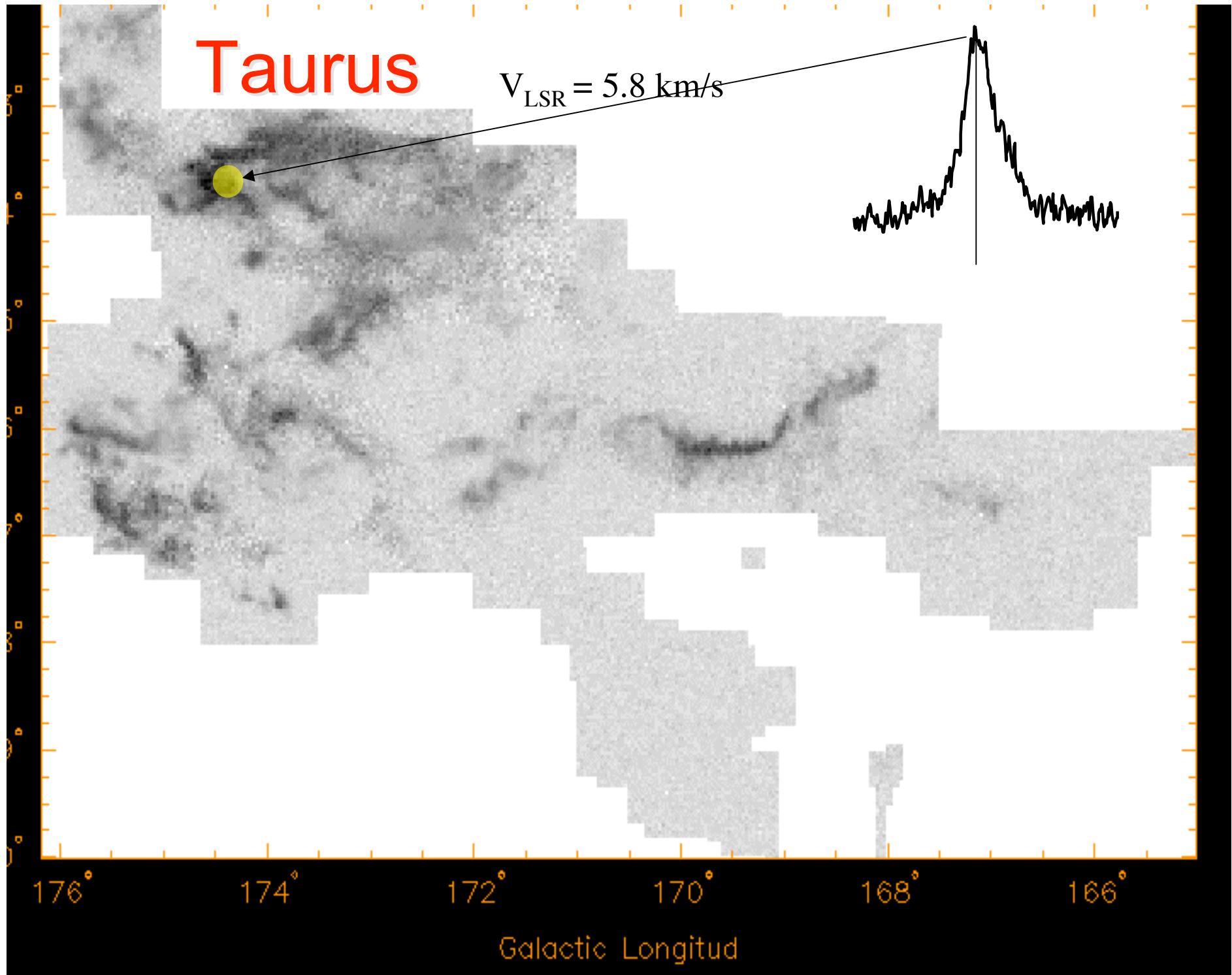


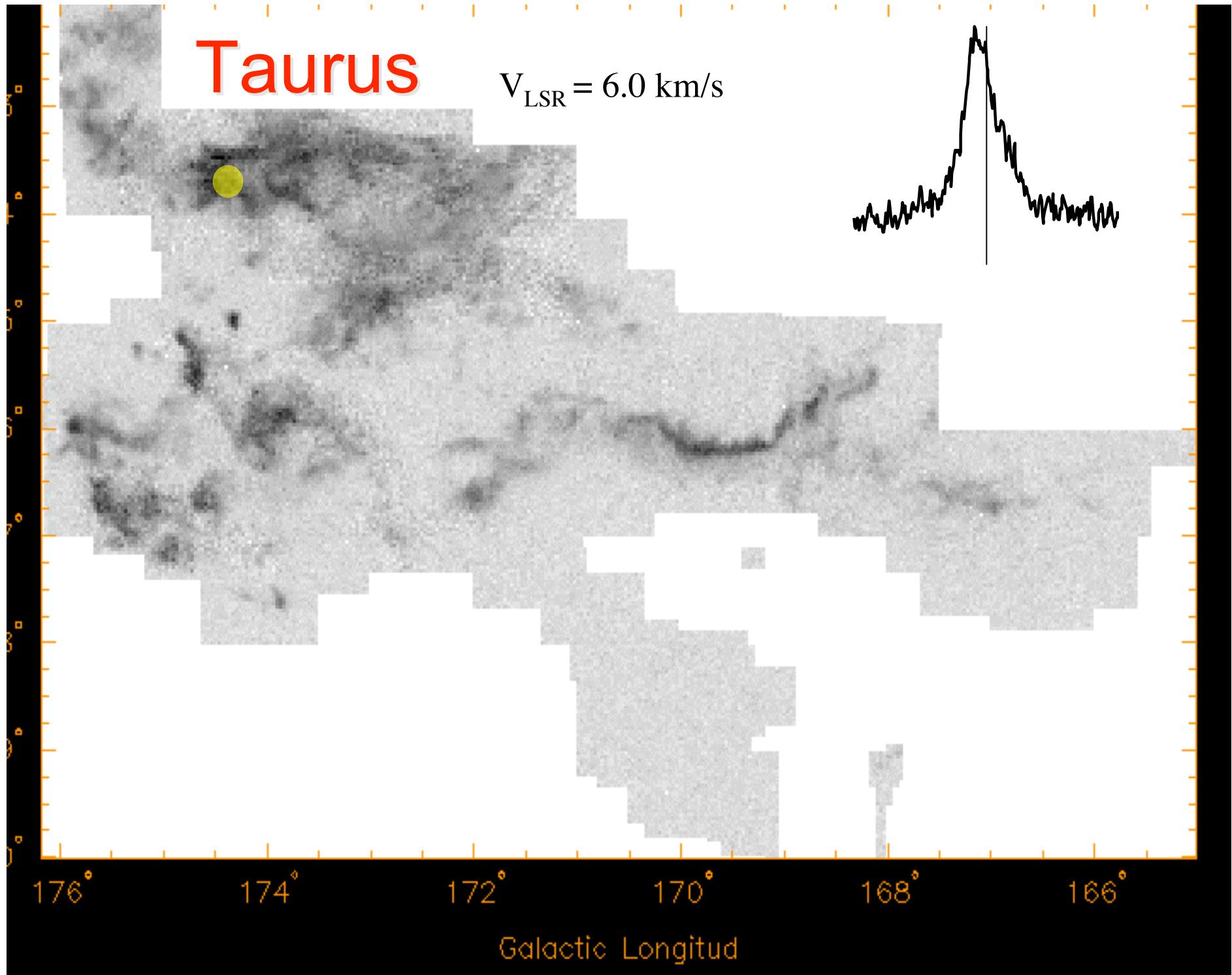


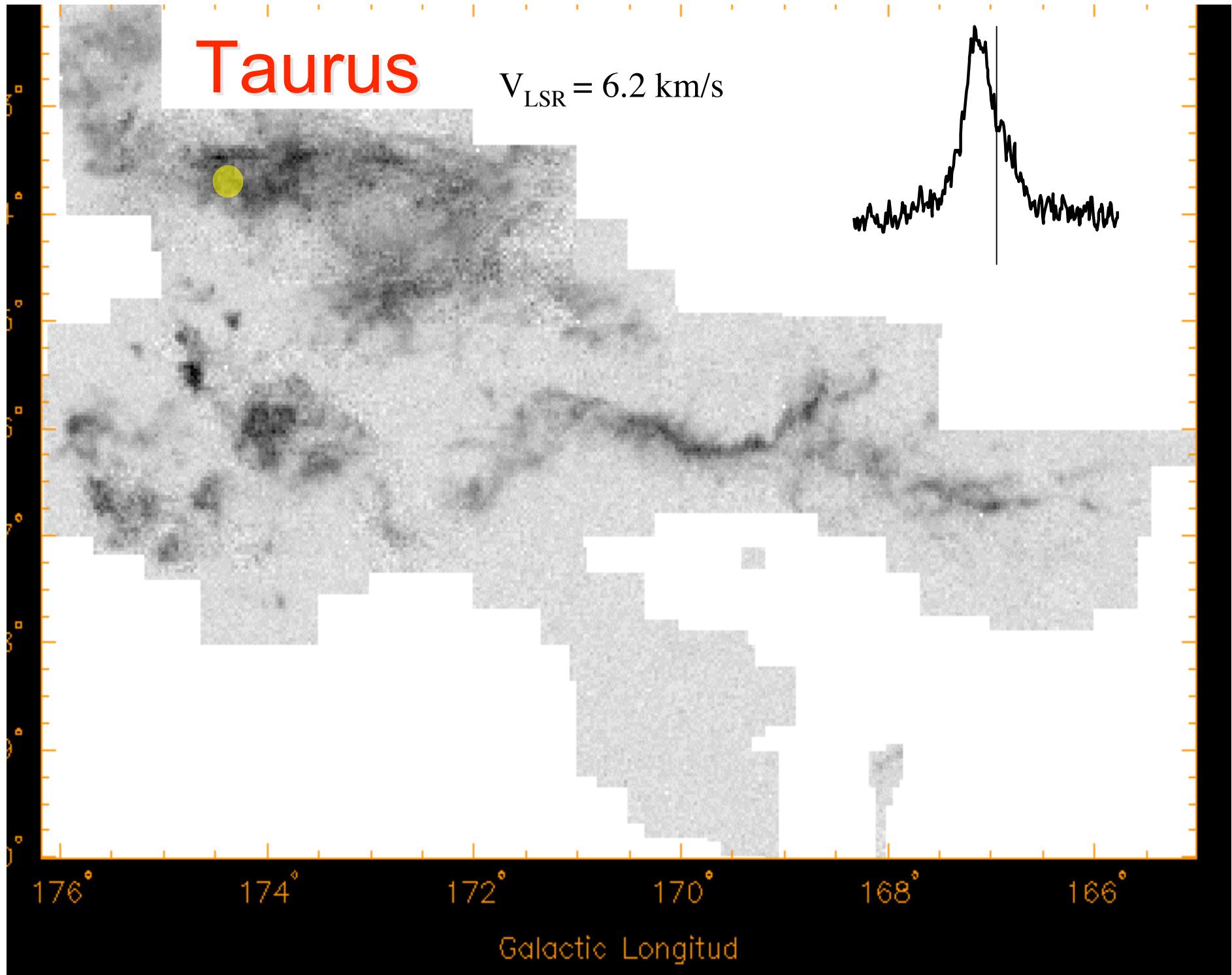


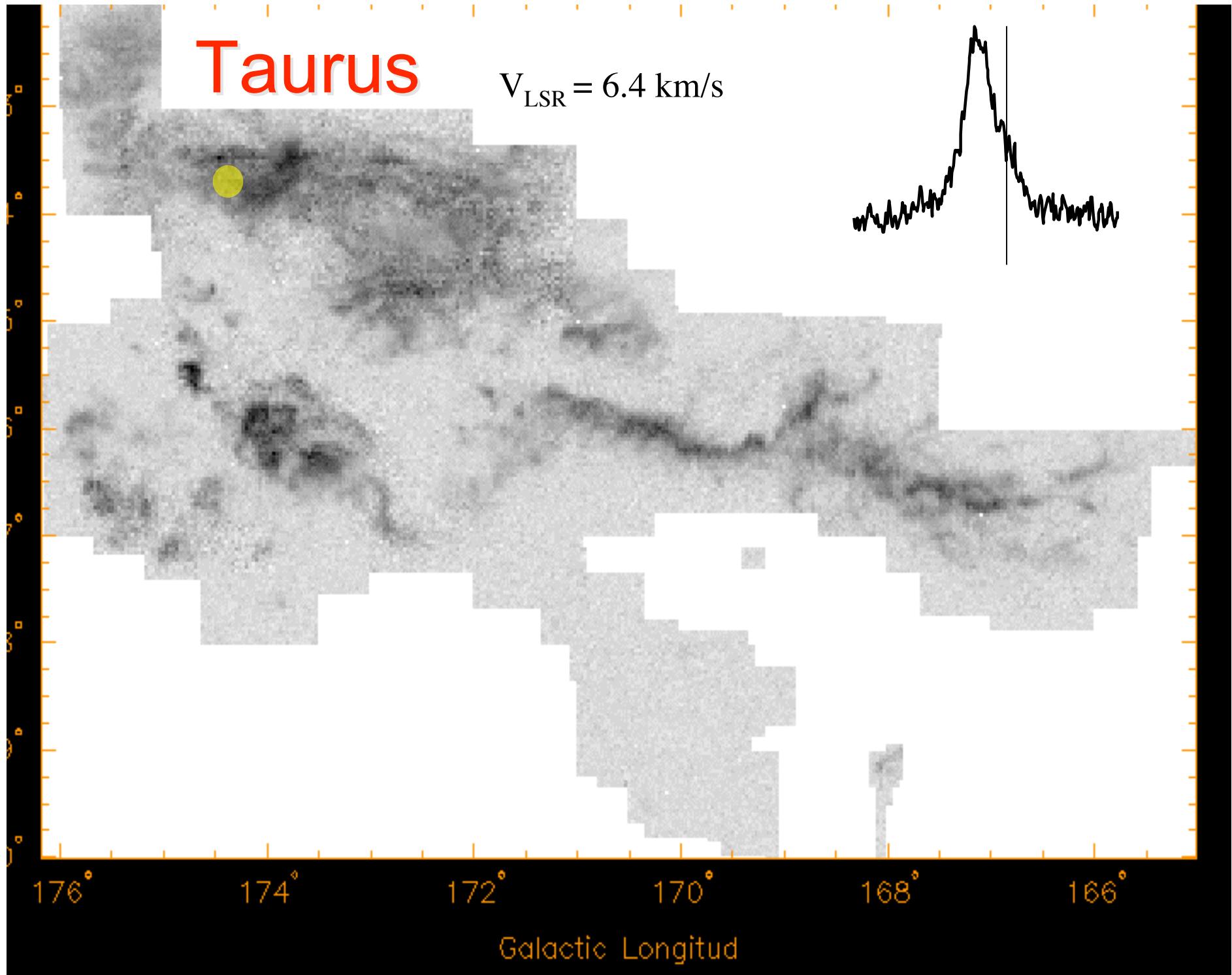


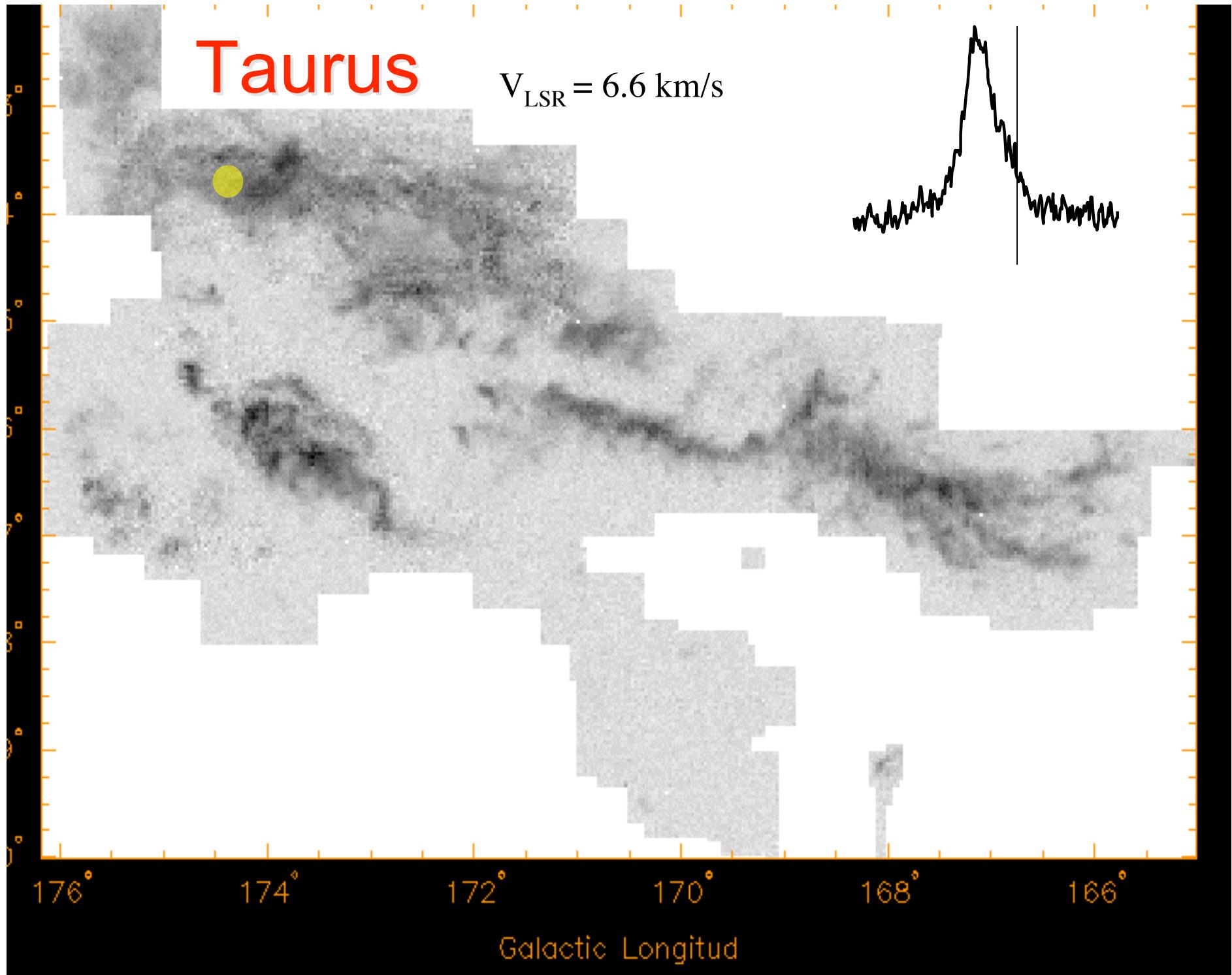


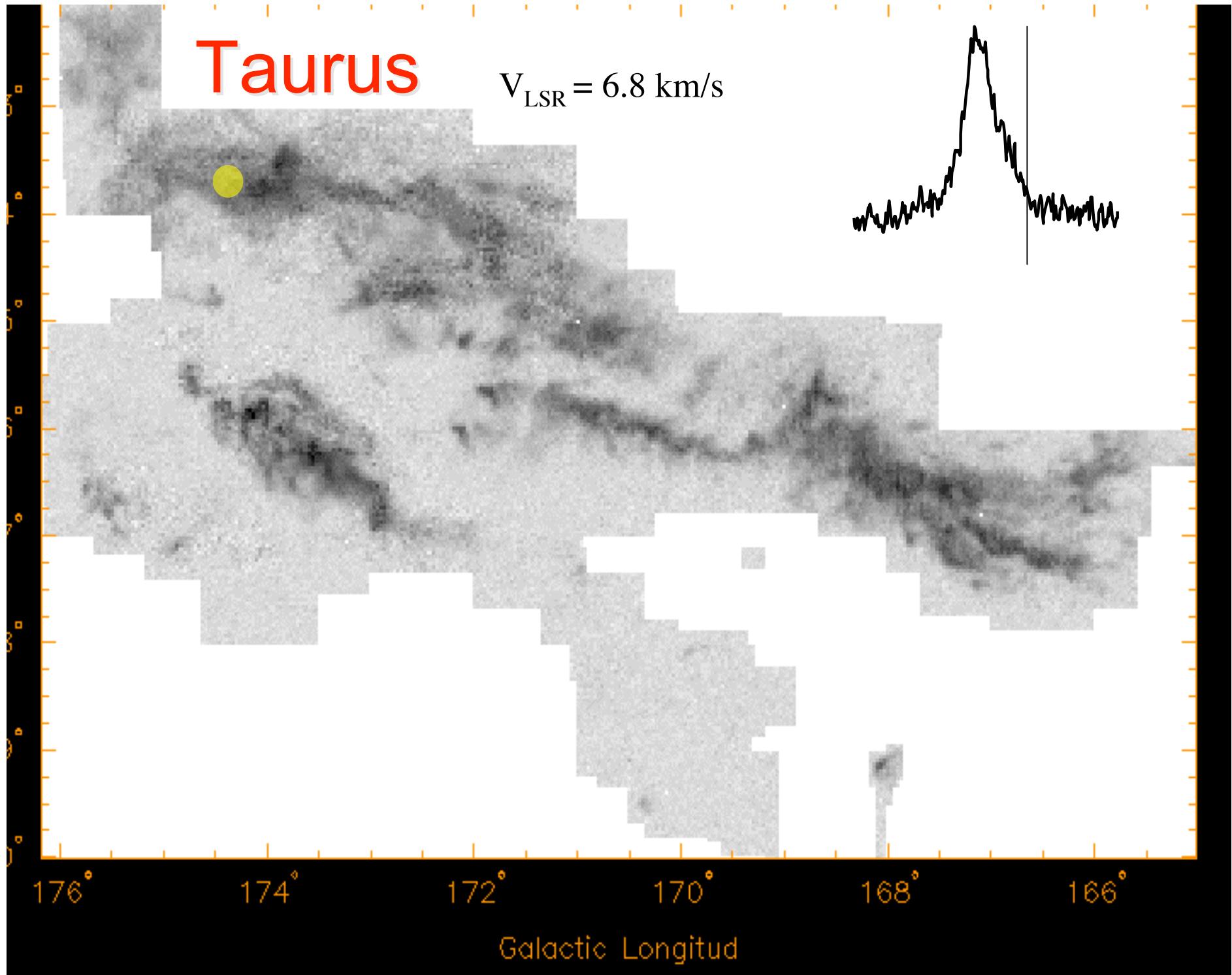


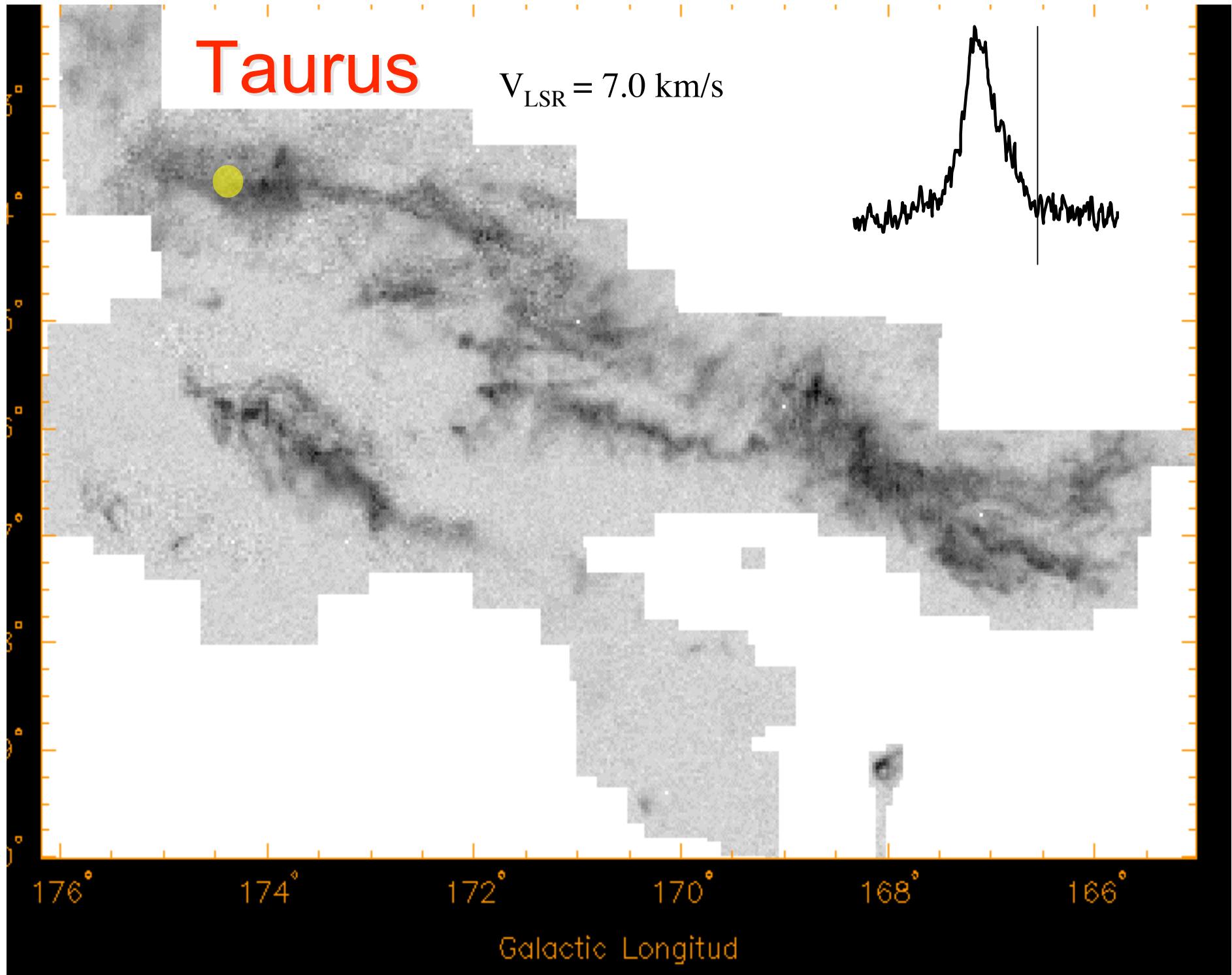






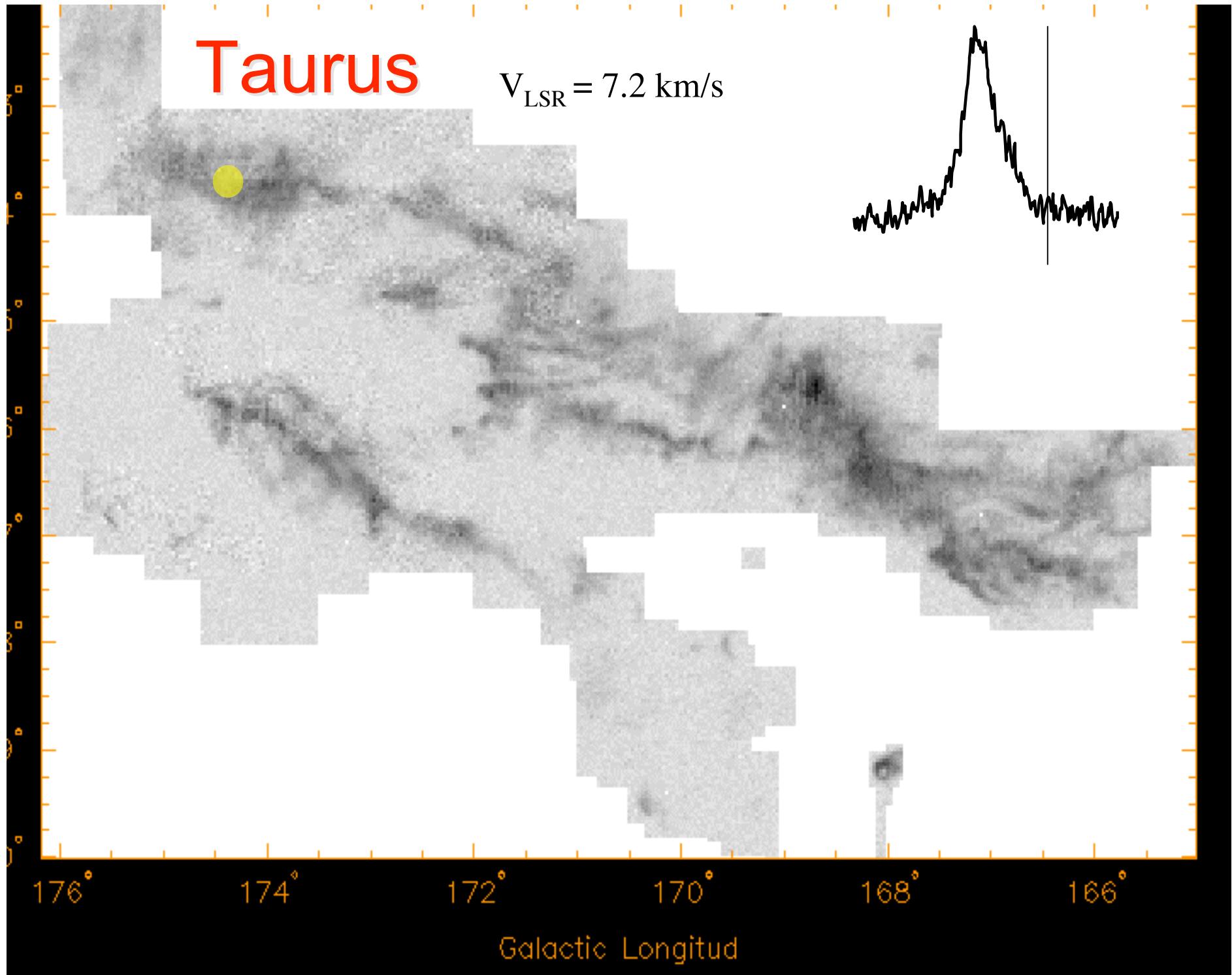


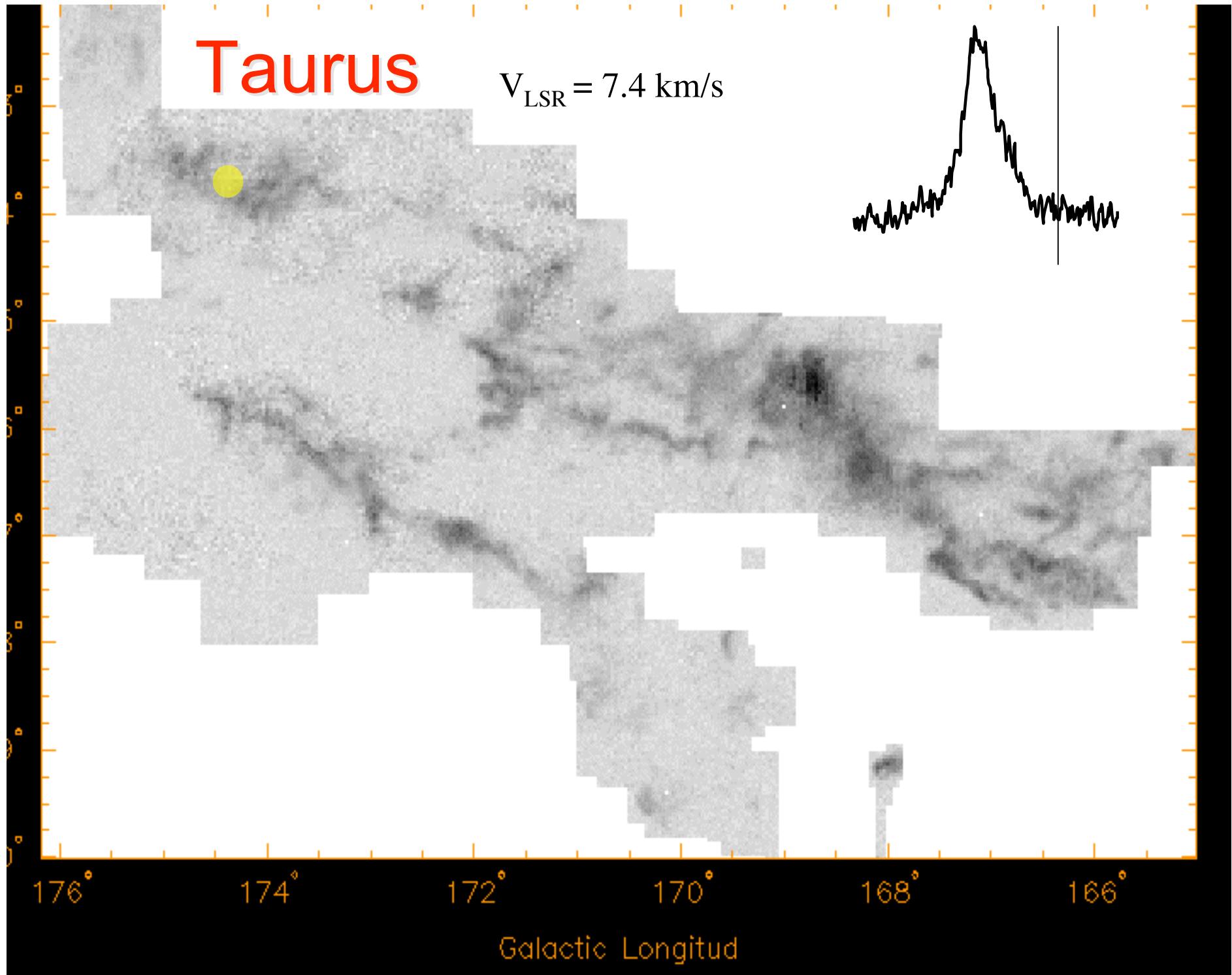


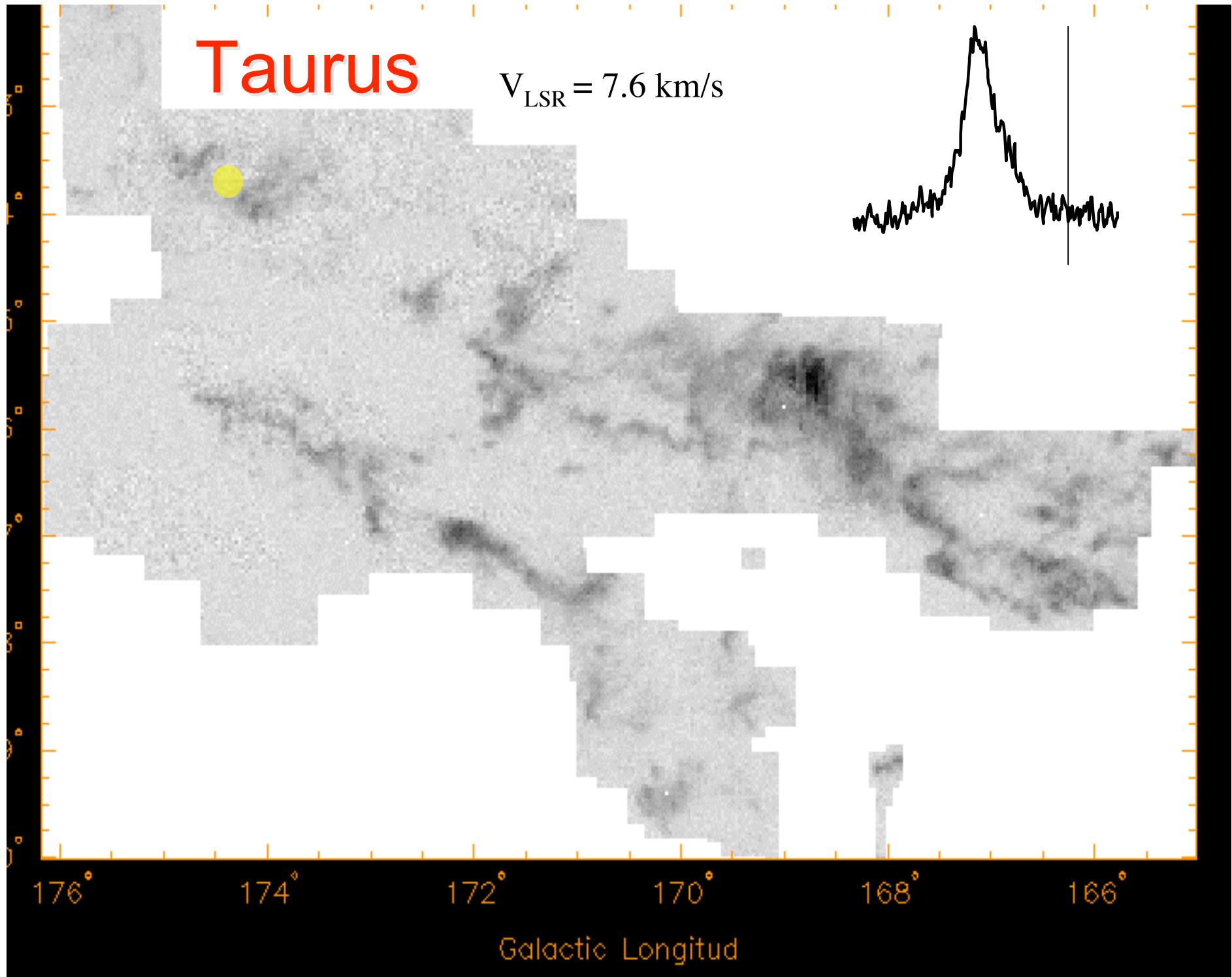


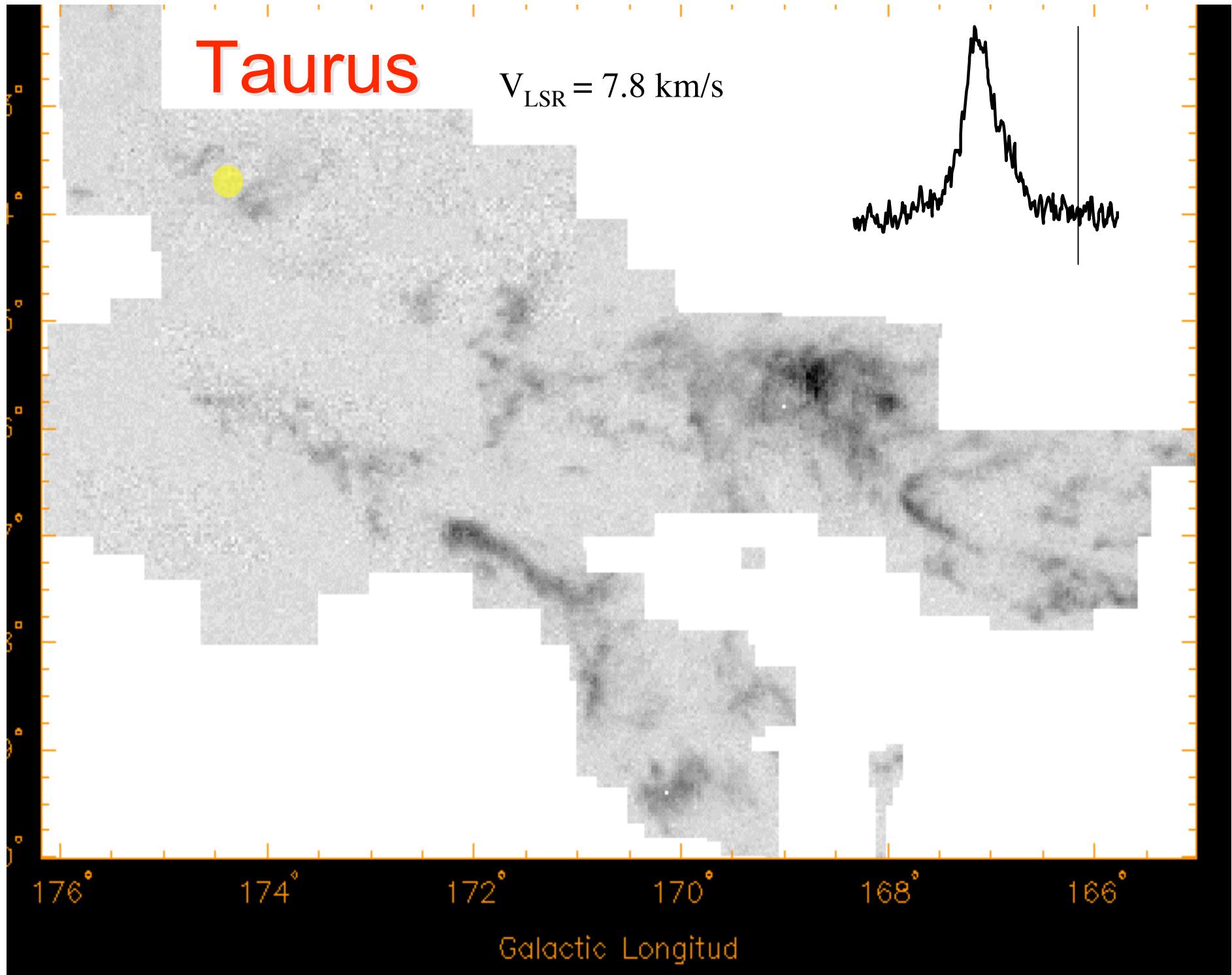
Taurus

$V_{\text{LSR}} = 7.0 \text{ km/s}$



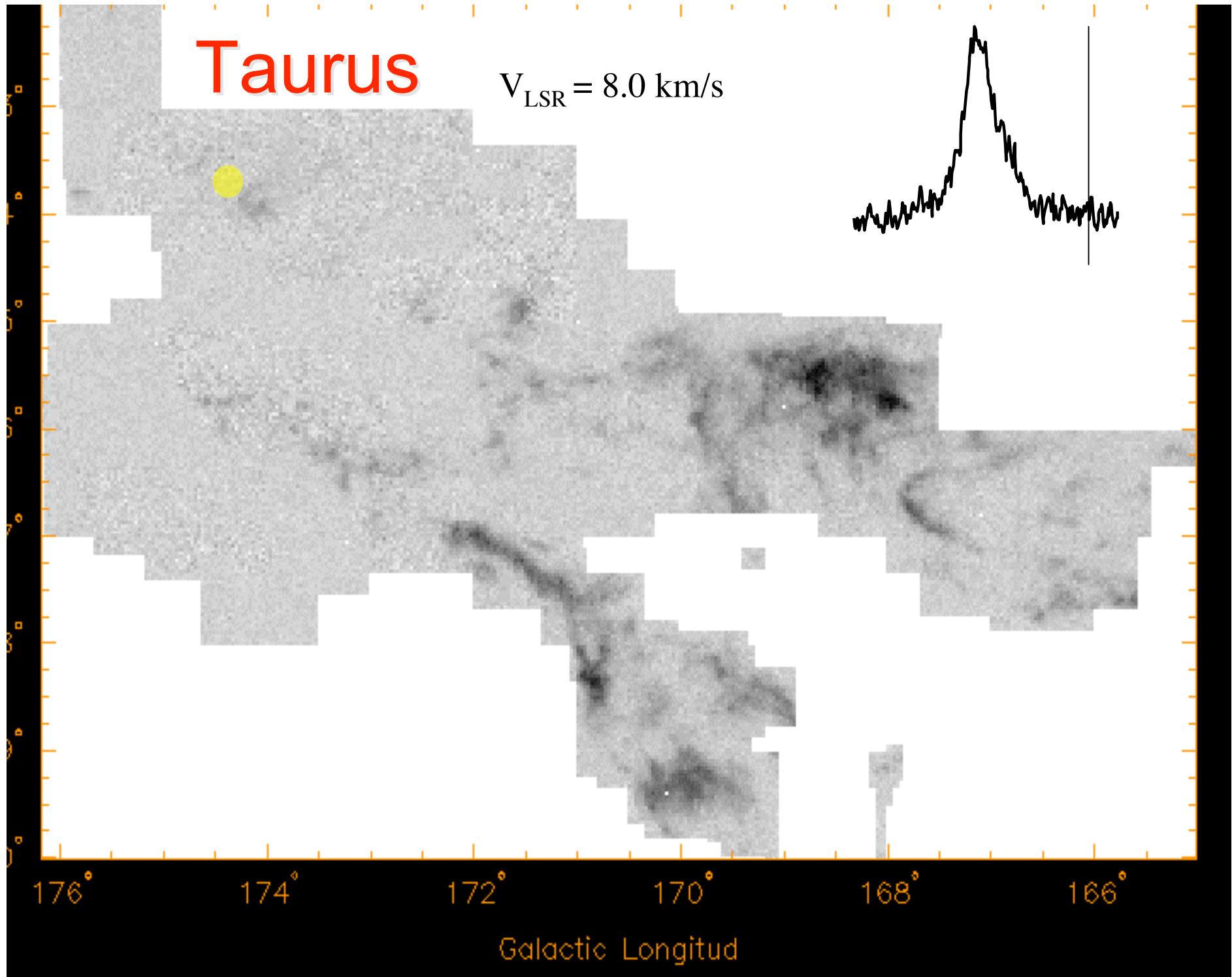


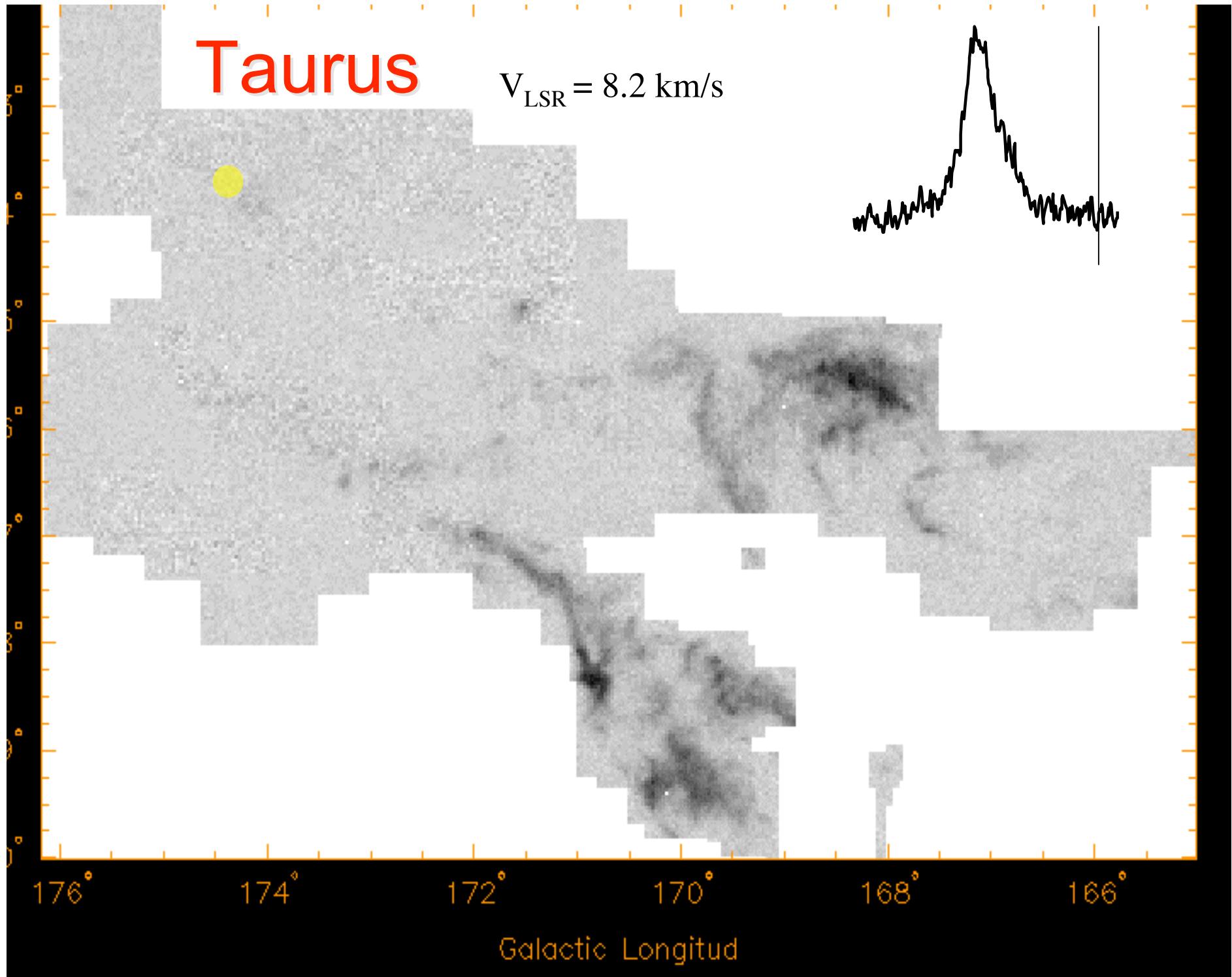


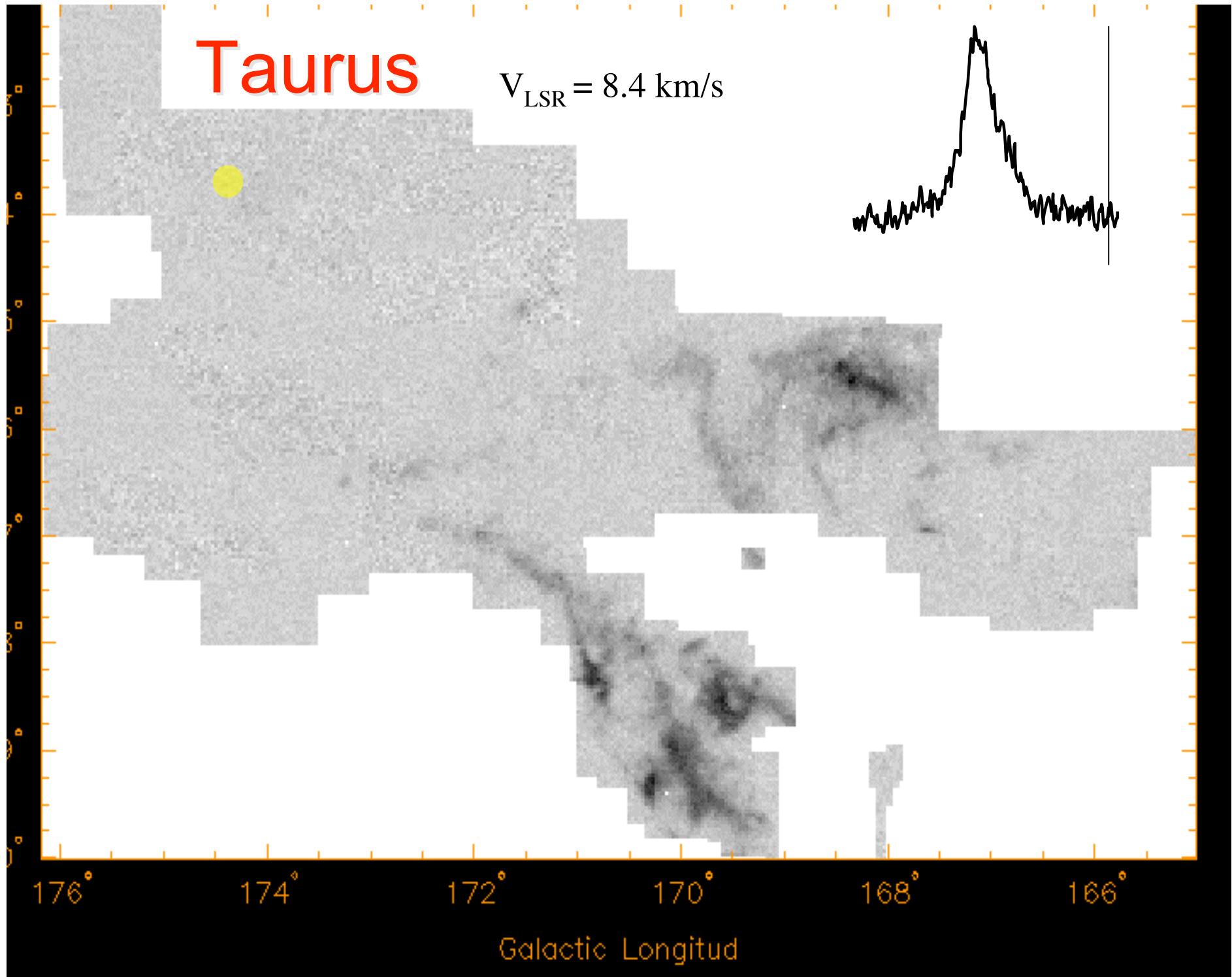


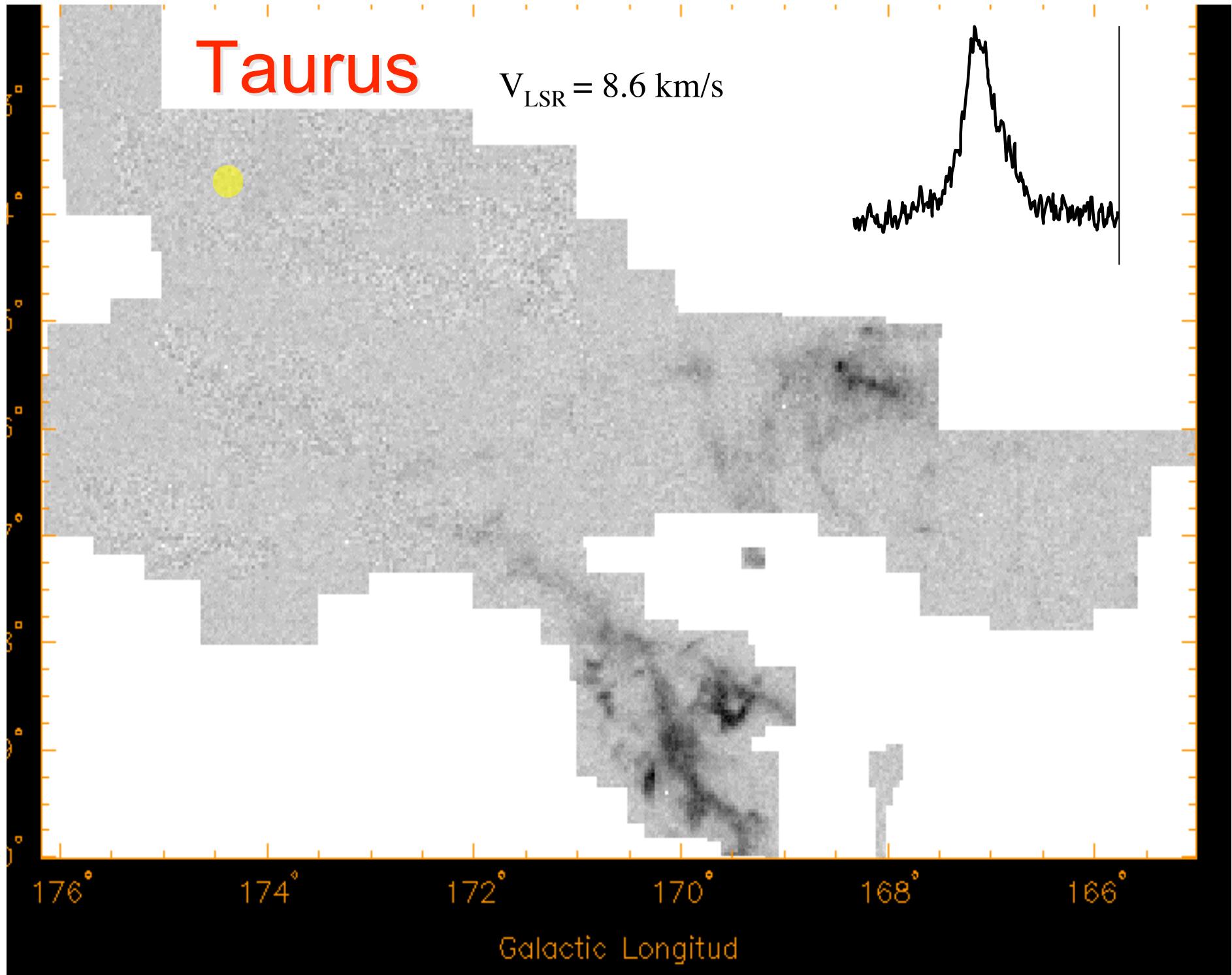
Taurus

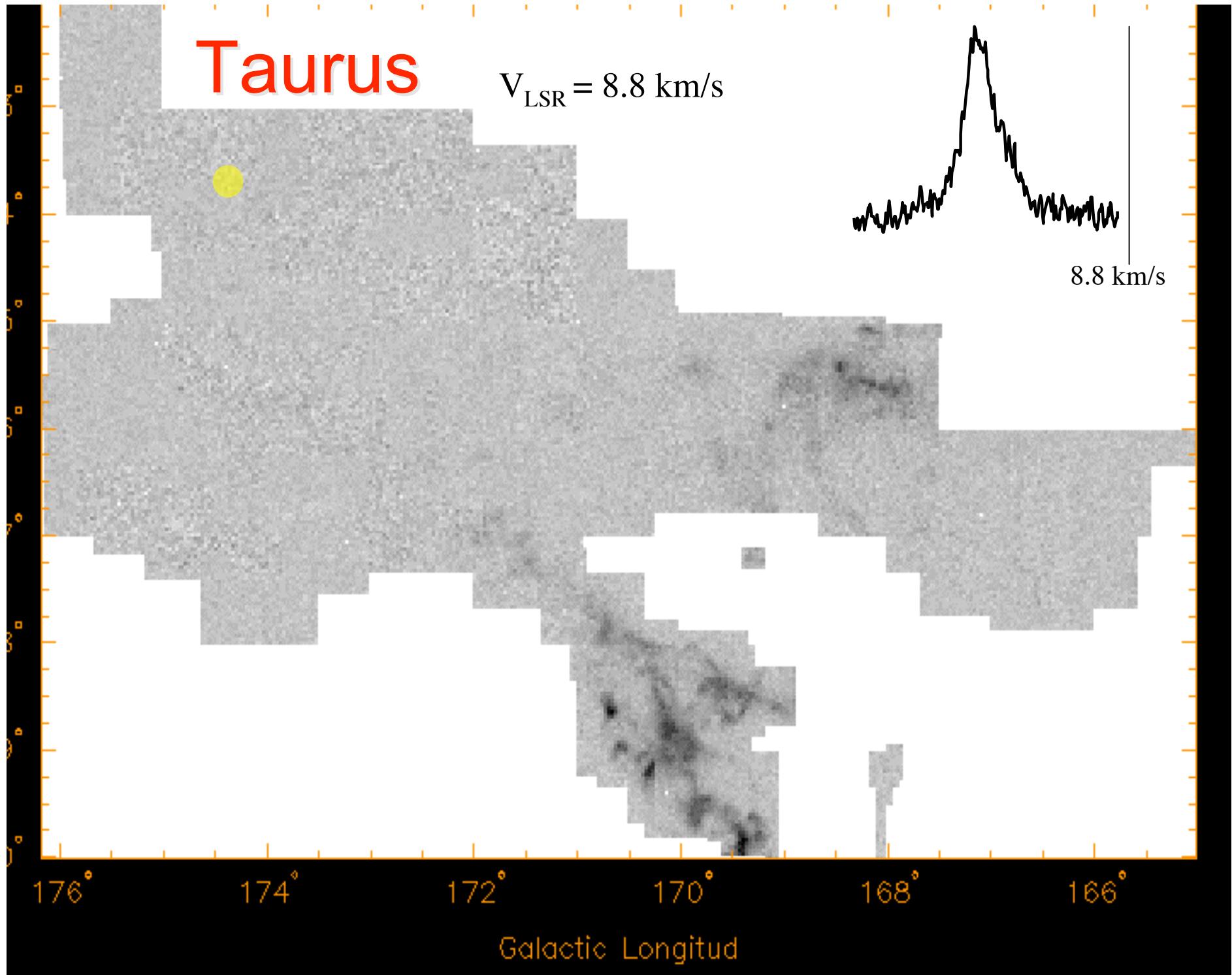
$V_{\text{LSR}} = 7.8 \text{ km/s}$

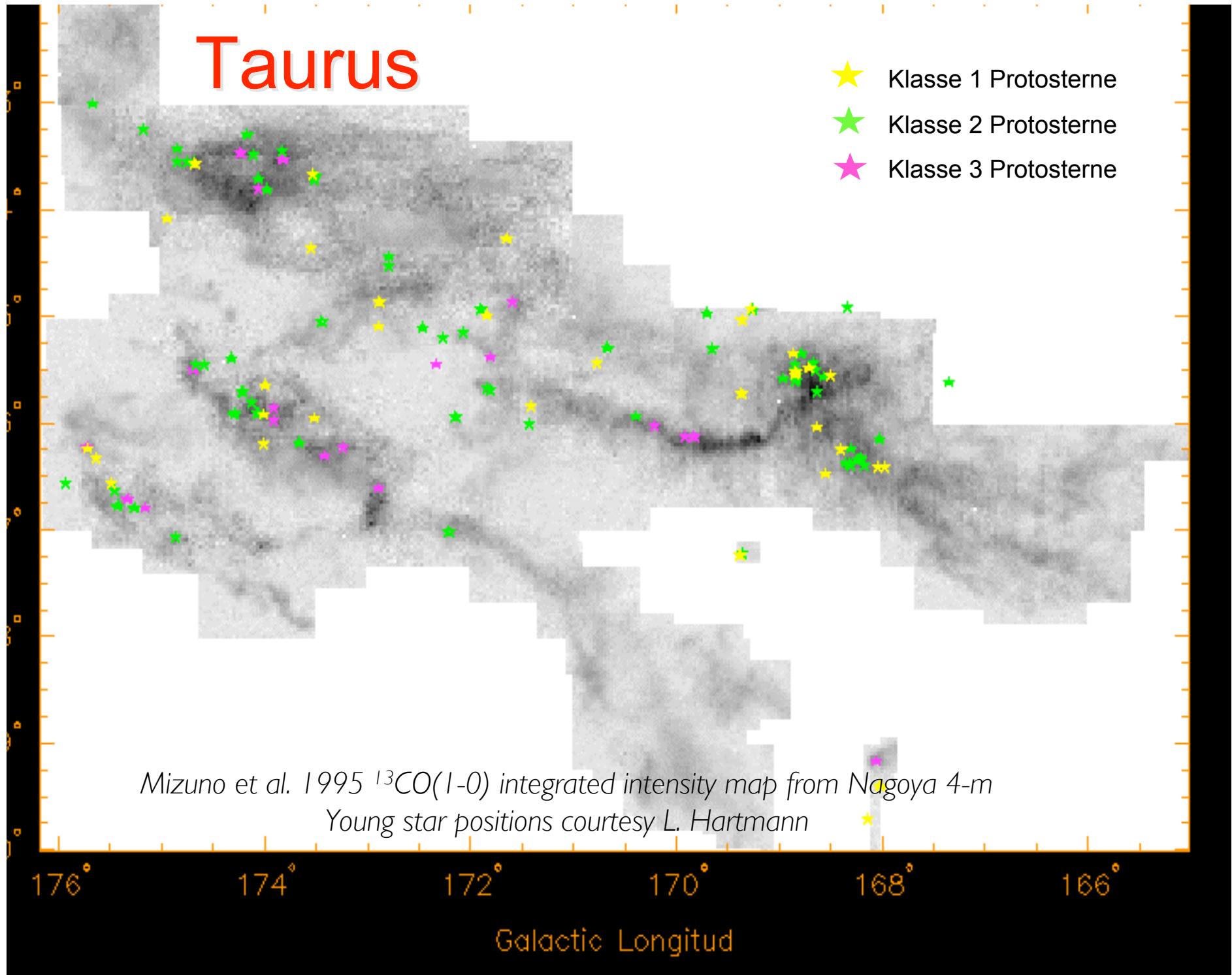












Hydrodynamics



- gases and fluids are *large* ensembles of interacting particles
- \rightarrow state of system is described by location in $6N$ dimensional phase space $f^{(N)}(\vec{q}_1 \dots \vec{q}_N, \vec{p}_1 \dots \vec{p}_N) d\vec{q}_1 \dots d\vec{q}_N d\vec{p}_1 \dots d\vec{p}_N$
- time evolution governed by ‘equation of motion’ for $6N$ -dim probability distribution function $f^{(N)}$
- $f^{(N)} \rightarrow f^{(n)}$ by integrating over all but n coordinates \rightarrow BBGKY hierarchy of equations of motion (after Born, Bogoliubov, Green, Kirkwood and Yvon)
- physical observables are typically associated with 1- or 2-body probability density $f^{(1)}$ or $f^{(2)}$
- at lowest level of hierarchy: 1-body distribution function describes the probability of finding a particle at time t in the volume element $d\vec{q}$ at \vec{q} with momenta in the range $d\vec{p}$ at \vec{p} .
- **Boltzmann equation** – equation of motion for $f^{(1)}$

$$\begin{aligned} \frac{df}{dt} &\equiv \frac{\partial f}{\partial t} + \dot{\vec{q}} \cdot \vec{\nabla}_{\text{q}} f + \dot{\vec{p}} \cdot \vec{\nabla}_{\text{p}} f \\ &= \frac{\partial f}{\partial t} + \vec{v} \cdot \vec{\nabla}_{\text{q}} f + \vec{F} \cdot \vec{\nabla}_{\text{p}} f = f_{\text{c}}. \end{aligned}$$

- o Boltzmann equation

$$\begin{aligned}\frac{df}{dt} &\equiv \frac{\partial f}{\partial t} + \vec{\dot{q}} \cdot \vec{\nabla}_q f + \vec{\dot{p}} \cdot \vec{\nabla}_p f \\ &= \frac{\partial f}{\partial t} + \vec{v} \cdot \vec{\nabla}_q f + \vec{F} \cdot \vec{\nabla}_p f = f_c.\end{aligned}$$

→ first line: transformation from comoving to spatially fixed coordinate system.

→ second line: velocity $\vec{v} = \vec{\dot{q}}$ and force $\vec{F} = \vec{\dot{p}}$

→ all higher order terms are 'hidden' in the collision term f_c

- o observable quantities are typically (velocity) moments of the Boltzmann equation, e.g.

→ density:

$$\rho = \int m f(\vec{q}, \vec{p}, t) d\vec{p}$$

→ momentum:

$$\rho \vec{v} = \int m \vec{v} f(\vec{q}, \vec{p}, t) d\vec{p}$$

→ kinetic energy density:

$$\rho \vec{v}^2 = \int m \vec{v}^2 f(\vec{q}, \vec{p}, t) d\vec{p}$$

- in general: the i -th velocity moment $\langle \xi_i \rangle$ (of $\xi_i = m\vec{v}^i$) is

$$\langle \xi_i \rangle = \frac{1}{n} \int \xi_i f(\vec{q}, \vec{p}, t) d\vec{p}$$

with the mean particle number density n defined as

$$n = \int f(\vec{q}, \vec{p}, t) d\vec{p}$$

- the equation of motion for $\langle \xi_i \rangle$ is

$$\int \xi_i \left\{ \frac{\partial f}{\partial t} + \vec{v} \cdot \vec{\nabla}_q f + \vec{F} \cdot \vec{\nabla}_p f \right\} d\vec{p} = \int \xi_i \{f_c\} d\vec{p},$$

which after some complicated rearrangement becomes

$$\frac{\partial}{\partial t} n \langle \xi_i \rangle + \vec{\nabla}_q (n \langle \xi_i \vec{v} \rangle) + n \vec{F} \langle \vec{\nabla}_p \xi_i \rangle = \int \xi_i f_c d\vec{p}$$

(Maxwell-Boltzmann transport equation for $\langle \xi_i \rangle$)

- if the RHS is zero, then ξ_i is a conserved quantity. This is only the case for first three moments, **mass** $\xi_0 = m$, **momentum** $\vec{\xi}_1 = m\vec{v}$, and **kinetic energy** $\xi_2 = m\vec{v}^2/2$.
- MB equations build a hierarically nested set of equations, as $\langle \xi_i \rangle$ depends on $\langle \xi_{i+1} \rangle$ via $\vec{\nabla}_{\mathbf{q}}(n\langle \xi_i \vec{v} \rangle)$ and because the collision term cannot be reduced to depend on ξ_i only.
 - need for a closure equation
 - in hydrodynamics this is typically the equation of state.

assumptions

- **continuum limit:**

- distribution function f must be a ‘smoothly’ varying function on the scales of interest → local average possible
- stated differently: the averaging scale (i.e. scale of interest) must be larger than the mean free path of individual particles
- stated differently: microscopic behavior of particles can be neglected
- concept of fluid element must be meaningful

- **only ‘short range forces’:**

- forces between particles are short range or saturate → collective effects can be neglected
- stated differently: correlation length of particles in the system is finite (and smaller than the scales of interest)



limitations

- shocks (scales of interest become smaller than mean free path)
- phase transitions (correlation length may become infinite)
- description of self-gravitating systems
- description of fully fractal systems

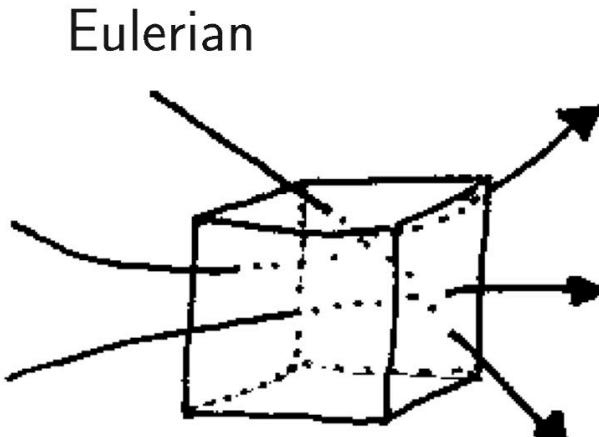


the equations of hydrodynamics

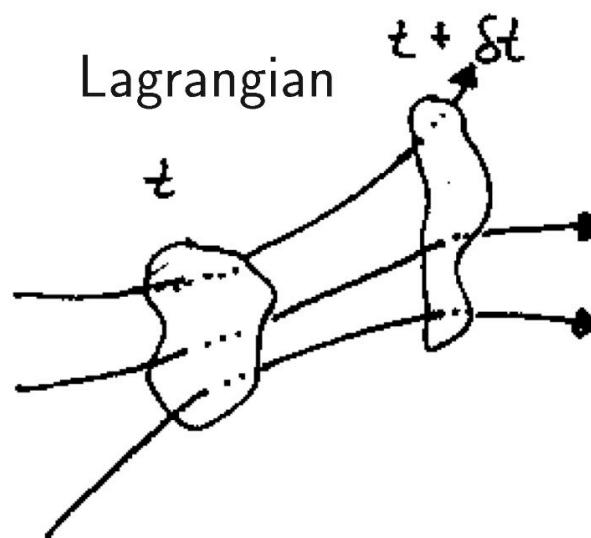
- hydrodynamics \equiv book keeping problem

One must keep track of the ‘change’ of a fluid element due to various physical processes acting on it. How do its ‘properties’ evolve under the influence of compression, heat sources, cooling, etc.?

- Eulerian vs. Lagrangian point of view



consider spatially fixed volume element



following motion of fluid element

- hydrodynamic equations = set of equations for the five conserved quantities (ρ , $\rho\vec{v}$, $\rho\vec{v}^2/2$) plus closure equation (plus transport equations for ‘external’ forces if present, e.g. gravity, magnetic field, heat sources, etc.)

- equations of hydrodynamics

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + \vec{v} \cdot \vec{\nabla} \rho = -\rho \vec{\nabla} \cdot \vec{v} \quad (\text{continuity equation})$$

$$\frac{d\vec{v}}{dt} = \frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} = -\frac{1}{\rho} \vec{\nabla} p - \vec{\nabla} \phi + \eta \vec{\nabla}^2 \vec{v} + \left(\zeta + \frac{\eta}{3}\right) \vec{\nabla} (\vec{\nabla} \cdot \vec{v}) \quad (\text{Navier-Stokes equation})$$

$$\frac{d\epsilon}{dt} = \frac{\partial \epsilon}{\partial t} + \vec{v} \cdot \vec{\nabla} \epsilon = T \frac{ds}{dt} - \frac{p}{\rho} \vec{\nabla} \cdot \vec{v} \quad (\text{energy equation})$$

$$\vec{\nabla}^2 \phi = 4\pi G \rho \quad (\text{Poisson's equation})$$

$$p = \mathcal{R} \rho T \quad (\text{equation of state})$$

$$\vec{F}_B = -\vec{\nabla} \frac{\vec{B}^2}{8\pi} + \frac{1}{4\pi} (\vec{B} \cdot \vec{\nabla}) \vec{B} \quad (\text{magnetic force})$$

$$\frac{\partial \vec{B}}{\partial t} = \vec{\nabla} \times (\vec{v} \times \vec{B}) \quad (\text{Lorentz equation})$$

ρ = density, \vec{v} = velocity, p = pressure, ϕ = gravitational potential, ζ and η viscosity coefficients, $\epsilon = \rho \vec{v}^2 / 2$ = kinetic energy density, T = temperature, s = entropy, \mathcal{R} = gas constant, \vec{B} = magnetic field (cgs units)

- mass transport – continuity equation

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + \vec{v} \cdot \vec{\nabla} \rho = -\rho \vec{\nabla} \cdot \vec{v}$$

(conservation of mass)

- transport equation for momentum – Navier Stokes equation

$$\frac{d\vec{v}}{dt} = \frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} = -\frac{1}{\rho} \vec{\nabla} p - \vec{\nabla} \phi + \eta \vec{\nabla}^2 \vec{v} + \left(\zeta + \frac{\eta}{3} \right) \vec{\nabla} (\vec{\nabla} \cdot \vec{v})$$

momentum change due to

→ pressure gradients: $(-\rho^{-1} \vec{\nabla} p)$

→ (self) gravity: $-\vec{\nabla} \phi$

→ viscous forces (internal friction, contains $\text{div}(\partial v_i / \partial x_j)$ terms):
 $\eta \vec{\nabla}^2 \vec{v} + \left(\zeta + \frac{\eta}{3} \right) \vec{\nabla} (\vec{\nabla} \cdot \vec{v})$

(conservation of momentum, general form of momentum transport: $\partial_t(\rho v_i) = -\partial_j \Pi_{ij}$)

- transport equation for internal energy

$$\frac{d\epsilon}{dt} = \frac{\partial \epsilon}{\partial t} + \vec{v} \cdot \vec{\nabla} \epsilon = T \frac{ds}{dt} - \frac{p}{\rho} \vec{\nabla} \cdot \vec{v}$$

- follows from the thermodynamic relation $d\epsilon = T ds - p dV = T ds + p/\rho^2 d\rho$ which described changes in ϵ due to entropy changed and to volume changes (compression, expansion)
- for adiabatic gas the first term vanishes ($s = \text{constant}$)
- heating sources, cooling processes can be incorporated in ds (conservation of energy)

- closure equation – equation of state
 - general form of equation of state $p = p(T, \rho, \dots)$
 - ideal gas: $p = \mathcal{R}\rho T$
 - special case – isothermal gas: $p = c_s^2 T$ (as $\mathcal{R}T = c_s^2$)

Note:

- in reality, computing the EOS is VERY complex!
- depends on detailed *balance* between *heating* and *cooling*
- these depend on *chemical composition* (which atomic and molecular species, dust)
- and on the ability to radiate away „cooling lines“ and black body radiation
--> problem of *radiation transfer*

Virial theorem



Derivation of virial theorem from momentum equation:

- consider pressure gradients, gravity, magnetic fields,
- neglect viscous forces

$$\text{LD} \quad \oint \frac{d\vec{v}}{dt} = - \vec{\nabla} p - g \vec{\nabla} \phi - \vec{\nabla} \left(\frac{B^2}{8\pi} \right) + \frac{1}{4\pi} (\vec{B} \cdot \vec{\nabla}) \vec{B}$$

pressure term gravity magnetic "pressure" magnetic tension

- in component form:

$$\oint \frac{dv_i}{dt} = - \frac{\partial p}{\partial x_i} - g \frac{\partial \phi}{\partial x_i} - \frac{\partial}{\partial x_i} \left(\frac{B^2}{8\pi} \right) + \frac{1}{4\pi} B_j \frac{\partial}{\partial x_i} B_j$$

- multiply by x_i and integrate over volume:
- consider terms by term:

$$\begin{aligned}
 ① \int_S x_i \frac{dv_i}{dt} dV &= \int_S x_i \frac{d^2 x_i}{dt^2} dV \\
 [\text{integrate by parts}] &= \int_S \frac{d}{dt} \left(x_i \frac{dx_i}{dt} \right) dV - \int_S \frac{dx_i}{dt} \frac{dx_i}{dt} dV \\
 &= \int_S \frac{d^2}{dt^2} \left(\frac{x_i x_i}{2} \right) dV - \int_S v_i v_i dV \\
 &= \frac{1}{2} \frac{d^2}{dt^2} \int_S x_i x_i dV - 2 \cdot \int_S \frac{1}{2} \rho v_i v_i dV \\
 &= \frac{1}{2} \overset{\circ\circ}{I} - 2T
 \end{aligned}$$

where $I = \int_S r^2 dV$ is called moment of inertia
 [but not quite, because no axis defined.]

and $T = \frac{1}{2} \int_S \rho v^2 dV$ is the kinetic energy
 [note, does not contain random
 = thermal motions]

$$\begin{aligned}
 \textcircled{i} \quad - \int x_i \frac{\partial P}{\partial x_i} dV &= - \underbrace{\int \frac{\partial}{\partial x_i} (x_i p) dV}_{\text{div}(\vec{x}p) \rightarrow \text{Gauss}} + \int p \frac{\partial x_i}{\partial x_i} dV \\
 &= - \oint x_i p \cdot dS_i + 3 \int p dV \\
 &= - \oint p \vec{r} \cdot d\vec{s} + 2U = -2T_S + 2U
 \end{aligned}$$

where

$$U = \text{thermal energy} = \frac{3}{2} \int p dV$$

and

$$\begin{aligned}
 T_S &= \text{surface term of kinetic} \\
 &\quad \text{energy} = \frac{1}{2} \oint p \vec{r} \cdot d\vec{s}
 \end{aligned}$$

$$\begin{aligned}
 \textcircled{iii} \quad \int g x_i \frac{\partial \phi}{\partial x_i} dV &= \int g \vec{r} \cdot \vec{F}_g dV \quad \vec{F}_g = -\vec{\nabla} \phi = \text{grav. force} \\
 &= \text{total potential energy} = \omega
 \end{aligned}$$

↳ neglecting magnetic fields for the moment,
we get:

$$\frac{1}{2} \ddot{\mathbf{I}} = 2 \cdot (\mathbf{T} - \mathbf{T}_S) + 2\mathbf{u} + \boldsymbol{\omega}$$

scalar virial theorem

- Virial theorem describes fundamental relation between morphological parameters (\mathbf{I} = tensor of inertia, $\boldsymbol{\omega}$ = tensor of potential energy) and kinematic quantities (tensor of kinetic energy) $K = \mathbf{T} + \mathbf{u} - \mathbf{T}_S$)

- in equilibrium: $\ddot{r} = 0$!

$$\hookrightarrow \boxed{2K + \omega = 0}$$

$K = T + U$, neglecting surface effects T_S

\hookrightarrow the system is called virialized.

- total energy: $\boxed{E_{\text{tot}} = K + \omega}$

in virial equilibrium it follows

$$\boxed{E_{\text{tot}} = K + \omega = \frac{\omega}{2} = -K}$$

virialized systems are always bound with binding energy equal to $-K$.

Virial Theorem applied to MC dynamics

- derivation & definition via effective pressure (\equiv energy density;
unit = erg/cm³)

* trace of tensor of inertia: $I = \int r^2 dm$

* evaluate $\ddot{I} = \frac{d\dot{I}}{dt^2}$ from equation of motion

$$*\quad \oint \frac{d\vec{r}}{dt} = -\vec{\nabla}P + \frac{1}{4\pi} (\vec{\nabla} \times \vec{B}) \times \vec{B} + \vec{g}$$

\uparrow \uparrow \uparrow
 $P = P_{th} + P_{thuk}$ mag. field gravity

* \hookrightarrow
$$\ddot{I} = \underbrace{2[T - T_S]}_{E_{kin}} + \underbrace{M}_{E_{mag}} + \underbrace{\omega}_{E_{pot}}$$

- kinetic energy = from thermal motion + bulk (turbulent) motion

$$* \boxed{T = \int_{\text{cloud volume}} \left(\frac{3}{2} P_{\text{th}} + \frac{1}{2} \bar{\rho} v^2 \right) dV = \underbrace{\frac{3}{2} \bar{\rho} V_{\text{cl}}}_{\text{mean pressure}} }$$

$$\left(\frac{3}{2} P_{\text{th}} = \frac{3}{2} \bar{\rho} c_s^2 \right)$$

* relate $\bar{\rho}$ to (observable) velocity dispersion along LOS

$$\sigma_{\text{LO}}^2 = \frac{1}{M} \int (c^2 + \frac{1}{3} v^2) dM = \frac{\bar{\rho}}{\bar{s}}$$

* surface term (often neglected, but may be important in interstellar turbulence)

here we assume cloud is embedded in ambient medium with constant pressure p_s

$$\boxed{T_s = \frac{1}{2} \int_{\text{surface}} p_s \vec{r} d\vec{s} = \frac{3}{2} p_s V_{\text{cl}}}$$

$$* \boxed{2(T - T_s) = 3(\bar{\rho} - p_s)V_{\text{cl}}}$$

- magnetic energy:

$$* \quad dU = \frac{1}{8\pi} \int_{\text{volume}} B^2 dV + \frac{1}{4\pi} \int_{\text{surface}} \vec{r} \cdot (\vec{B} \cdot \vec{B} - \frac{1}{2} B^2 \mathbb{I}) \cdot d\vec{s}$$

- * if stresses in ambient medium small \rightarrow assume field is force free there; then

$$\boxed{dU = \frac{1}{8\pi} \int_{\text{volume}} (B^2 - B_0^2) dV}$$

↑
fieldstrength in cloud
↓
far from cloud

NB:

$$1 \text{ Gauß} = 1 \sqrt{\frac{\text{esu}}{\text{cm} \cdot \text{s}^2}} \\ = 10^{-4} \text{ Tesla}$$

- gravitational energy:

* $\boxed{\omega = \int_{\text{Volume}} \rho \vec{r} \cdot \vec{g} dV = -\frac{3}{5} \xi \left(\frac{GM^2}{R} \right)}$ with $\xi \approx 1$

* now: define "gravitational" pressure:

$$\boxed{\omega = -3 \rho_g \cdot V_{cl}}$$

* intuitively, ρ_g is the mean weight of the material in the cloud

$$\boxed{\rho_g = \frac{3\pi G}{20} \Sigma^2 \rightarrow 1.4 \cdot 10^5 \left(\frac{\bar{N}_H}{10^{22} \text{ cm}^{-2}} \right)^2 \text{ K} \cdot \text{cm}^{-3}}$$

with $\Sigma = \frac{M}{\pi R^2} = \mu_H \bar{N}_H$ and evaluated for cloud with $n_H(R) \propto 1/R$.

- in steady state (virial equilibrium): $\ddot{I} = 0$

$$\rightarrow \boxed{\bar{P} = P_s + P_g \cdot \left(1 - \frac{c\mu}{|\omega|}\right)}$$

i.e.: mean pressure inside cloud is surface pressure plus weight of material inside cloud reduced by magnetic stresses (reduction factor $c\mu/|\omega|$)

- total energy:

$$\boxed{E = T + c\mu + \omega \\ = \frac{3}{2} \left(P_s + P_g \left[1 - \frac{c\mu}{|\omega|} \right] \right) \cdot V_{cl}}$$

$E < 0$ bound

$E > 0$ unbound

- are MC's bound?

* in solar vicinity $\rho \approx 2.8 \cdot 10^4 \text{ K cm}^{-3}$

$\hookrightarrow 0.7 \cdot 10^4 \text{ K cm}^{-3}$ due to cosmic rays
 $0.3 \cdot 10^4 \text{ K cm}^{-3}$ due to B -field

$$\hookrightarrow \rho_s \approx 1.8 \cdot 10^4 \text{ K cm}^{-3}$$

* what is minimum ρ_g ?

visual extinction in order to get N_2
 $A_v \geq 2$

$$\hookrightarrow \rho_g \geq 2 \cdot 10^4 \text{ K cm}^{-3}$$

* \Rightarrow MC's are at least marginally bound.

Typically: $A_v \gg 2$

(typical values: $\rho_g \approx 2 \cdot 10^5 \text{ K cm}^{-3}$)

- filling factor: MC's are highly clumped
- * mean densities: $\langle n_H \rangle \approx 10^3 \dots 1,2 \cdot 10^4 \text{ cm}^{-3}$ \Rightarrow say $n_H \approx 3000 \text{ cm}^{-3}$
- * with $M \propto \langle n_H \rangle R^3$
- * and $\langle N_H \rangle \propto \langle n_H \rangle \cdot R$ } we have $\langle n_H \rangle = 84 \text{ cm}^{-3} \left(\frac{M}{10^6 M_\odot} \right)^{-1/2} \left(\frac{\langle N_H \rangle}{1,5 \cdot 10^{22} \text{ cm}^{-2}} \right)$

\hookrightarrow filling factor:
$$f \equiv \frac{\langle n_H \rangle}{n_H} \approx 0,084 \cdot \left(\frac{M}{10^6 M_\odot} \right)^{-1/2} \left(\frac{n_H}{10^3 \text{ cm}^{-3}} \right)^{-1/2} \left(\frac{\langle N_H \rangle}{1,5 \cdot 10^{22} \text{ cm}^{-2}} \right)$$

PS: Clouds $M \leq 10^4 M_\odot$ must have $n_H > 10^3 \text{ cm}^{-3}$ to have the column densities found by Solomon et al.

- * difference between mass weighted and volume weighted gas distribution

- Magnetic Field vs. Gravity

↳ derivation of magnetically critical mass

* total energy: $E = T + \mathcal{M} + W$

$$= \frac{3}{2} [P_S + P_G \left(1 - \frac{\mathcal{M}}{|W|} \right)]$$

* collapse possible if $E < 0$, and assuming (incorrectly, though!) $P_S = 0$

$$\rightarrow \text{collapse if } \underbrace{1 - \frac{\mathcal{M}}{|W|}}_{< 0} !$$

* recall: $\mathcal{M} = \frac{1}{8\pi} \int (B^2 - B_0^2) dV$
volume

$$= \frac{1}{8\pi} \int \bar{B}^2 dV = \left(\frac{5}{3}\right) \bar{B}^2 R^3 \quad \gamma \approx 1$$

Magnetic flux: $\underline{\Phi} = \int_{\text{fläche}} 2\pi R B dR = \pi R^2 \cdot \bar{B}$

↳ $\underline{\mathcal{M} = \left(\frac{\gamma}{3\pi^2}\right) \frac{\Phi^2}{R}}$

$$\hookrightarrow \mu = \left(\frac{J}{3\pi^2} \right) \frac{\Phi^2}{R}$$

also: $\omega = \int_{\text{Volume}} g^2 \cdot \dot{g} dV = - \frac{3}{5} \xi \left(\frac{GM^2}{R} \right)$ $\xi \approx 1$

* \hookrightarrow critical value: $\mu_{\text{crit}} = |\omega|$

$$\frac{\xi}{3\pi^2} \cdot \frac{\Phi^2}{R} = \frac{3}{5} \xi \frac{GM^2}{R}$$

note the same radial dependency!

$$\hookrightarrow M_{\text{crit}}^1 = \left(\frac{5\xi}{9\pi^2} \right) \cdot \frac{\Phi}{G^{1/2}}$$

$C \Phi \propto \frac{1}{2\pi}$

in the absence of
ambipolar diffusion
a mag. subcritical cloud
will remain so forever.

$$M_{\text{crit}} \approx (4 \cdot 10^6 M_\odot) \cdot \left(\frac{n(H_2)}{1 \text{ cm}^{-3}} \right)^2 \cdot \left(\frac{B}{3 \mu G} \right)^3$$

* critical mass-to-flux ratio:

$$\left(\frac{M}{\Phi}\right)_{\text{crit}} = \left(\frac{55}{3\pi^2 G}\right) G^{-1/2} = 0,16 \dots 0,18 \cdot G^{-1/2}$$

$$1G = 1 \cdot g^{1/2} \text{ cm}^{-1/2} \text{ s}^{-1} \quad [\text{B}]$$

$$1 \text{ esu} = 1 \cdot g^{1/2} \text{ cm}^{3/2} \text{ s}^{-1} \quad [\text{q}]$$

$$\text{Grav. const. } G = 6,67 \cdot 10^{-8} \text{ cm}^3 \text{ g}^{-1} \text{ s}^{-2}$$

depending on geometry
and further details

Observations:

typical molecular cloud cores are
magnetically supercritical with
 $\left(\frac{M}{g}\right) \approx 2 \dots 3 \times \left(\frac{M}{\Phi}\right)_{\text{crit}}$
 (Crutcher 1999, Bourke et al. 2001)

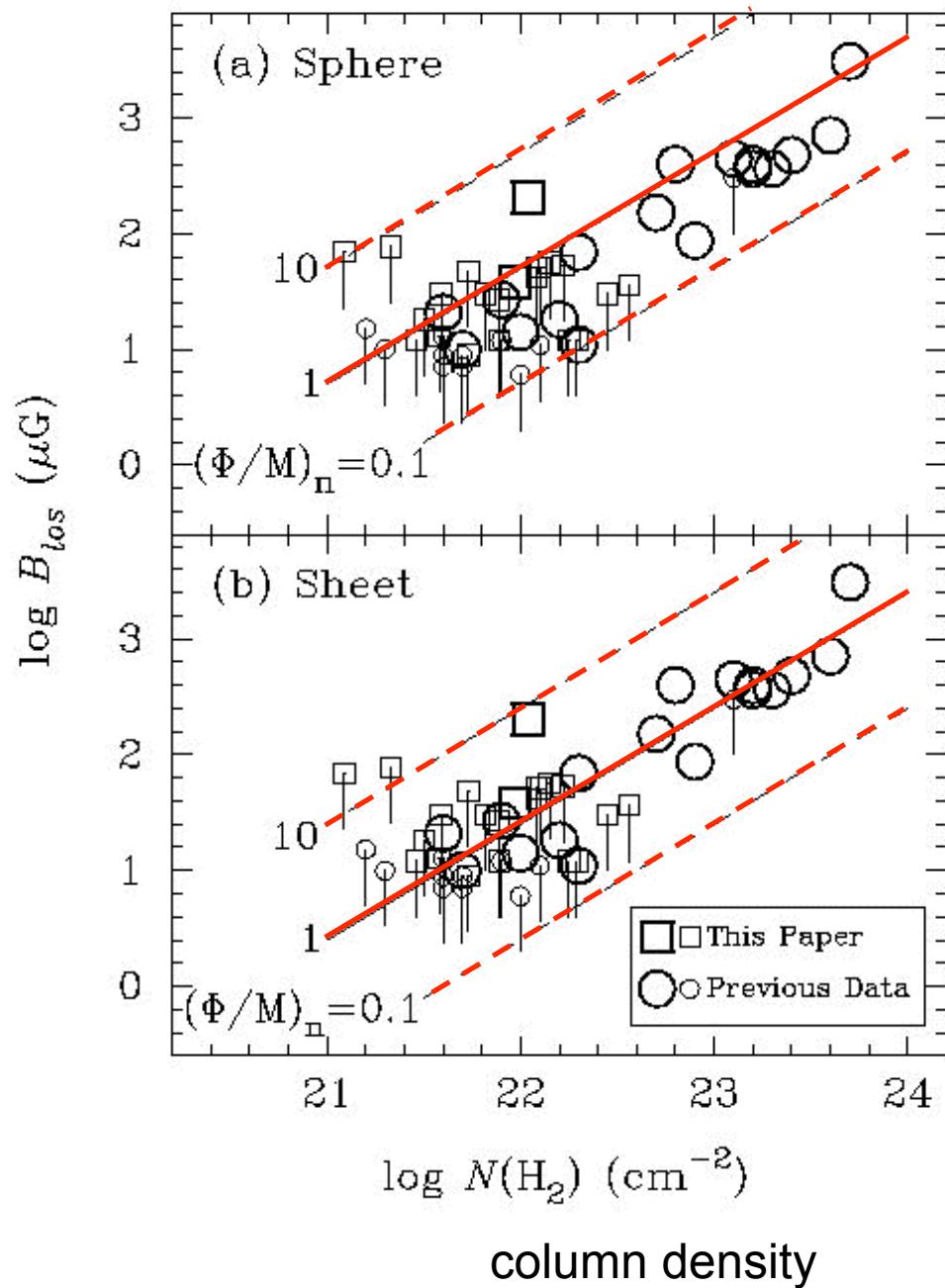
B versus $N(H_2)$ from Zeeman measurements.

(from Bourke et al. 2001)

→ cloud cores are
marginally
magnetically
supercritical!!!

$(\Phi/M)_n > 1$ no collapse
 $(\Phi/M)_n < 1$ collapse

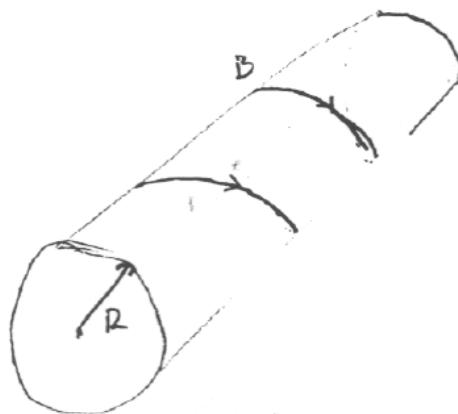
observed B-field



NON-ideal MHD:

diffusion between neutral gas and charged particles \rightarrow ambipolar diffusion

- only charged particles couple directly to the B field
- neutrals "see" the field only via collisions with electrons & ions!
- example:



- estimate timescale for drift across cylinders with radius R with typical bend of B -field of order R .
- then Lorentz force $F_L \approx \frac{B^2}{4\pi R}$

from momentum equation: Balance between Lorentz force and s-i-n-drift:

$$\frac{1}{4\pi} (\vec{\nabla} \times \vec{B}) \times \vec{B} = \alpha \rho_i \rho_n \underbrace{(\vec{v}_i - \vec{v}_n)}_{\vec{v}_d}$$

coupling coefficient $\alpha = \frac{\langle \sigma v \rangle}{m_i + m_n}$
 $\approx 9.2 \cdot 10^{-13}$

$$\hookrightarrow \tau_{AD} = \frac{R}{v_0} = \left[\frac{4\pi \alpha \rho_i \rho_n R}{(\vec{\nabla} \times \vec{B}) \times \vec{B}} \right] \approx \frac{4\pi \alpha \rho_i \rho_n R^2}{B^2}$$

$$\tau_{AD} = \frac{R}{v_0} = \left[\frac{4\pi \alpha S_i B_n R}{(\vec{r} + \vec{B}) \times \vec{B}} \right] \approx \frac{4\pi \alpha S_i B_n R^2}{B^2}$$

$$\tau_{AD} \approx 25 \text{ Myr} \quad \left(\frac{B}{3 \mu\text{G}} \right)^{-2} \left(\frac{n(H_2)}{10^2 \text{ cm}^{-3}} \right)^2 \left(\frac{R}{1 \text{ pc}} \right)^2 \left(\frac{\chi}{10^{-6}} \right)$$

compare with gravitational free-fall time:

$$\tau_{ff} = \left(\frac{3\pi}{32 G} \right)^{1/2} g^{-1/2}$$

define: $\gamma = \frac{\tau_{AD}}{\tau_{ff}}$ \Rightarrow typically $\gamma \approx 10$ in MC's !

Jeans condition



Gravitational instability:

Jeans criterion

- after the first approach to determine stability properties is to analyze the linearized set of equations and derive a dispersion relation for the perturbation assumed.
- Linearized eqn.'s for isothermal self-gravitating fluid:

$$\frac{\partial \delta_1}{\partial t} + g_0 \vec{\nabla} \vec{v}_1 = 0 \quad \text{continuity}$$

$$\frac{\partial \vec{v}_1}{\partial t} = - \vec{\nabla} c_s^2 \frac{\delta_1}{g_0} - \vec{\nabla} \phi_1 \quad \text{momentum}$$

$$\vec{\nabla}^2 \phi_1 = 4\pi G g_1 \quad \text{Poisson}$$

- ▲ $\vec{\nabla} c_s^2 \frac{\delta_1}{g_0} = \frac{1}{g_0} \vec{\nabla} p_1$ with $p_1 = c_s^2 \rho_1$ from EOS.
- ▲ neglecting viscous effects ($\gamma = \xi = 0$)
- ▲ equilibrium characterized by $g_0 = \text{const.}$ and $\vec{v}_0 = 0$
- ▲ Jeans swindle: Poisson's eqn. considers only perturbed potential (\rightarrow set $\phi_0 = 0$)

- with $\frac{\partial}{\partial t}$ [continuity] + $\vec{\nabla}$ [momentum] it follows:

$$\frac{\partial^2 \rho_1}{\partial t^2} - c_s^2 \vec{\nabla}^2 \rho_1 - 4\pi G \rho_0 \rho_1 = 0$$

↳ wave equation for $\rho_1(\vec{x}, t)$

- analyze in Fourier space:

$$\rho_1(\vec{x}, t) = \int d^3k A(\vec{k}) e^{i[\vec{k}\vec{x} - \omega(\vec{k})t]}$$

$$\frac{\partial}{\partial t} \mapsto i\omega$$

$$\vec{\nabla} \mapsto i\vec{k}$$

- dispersion relation:

$$\omega^2 = c_s^2 k^2 - 4\pi G g_0$$

- ▲ if density g_0 is small \rightarrow disp. rel. of sound waves $\omega^2 = c_s^2 k^2$
- ▲ or small wavelength $\lambda = \frac{2\pi}{k}$
- ▲ self-gravity acts "strongest" on large scales (small k)
[gravity is long-range force]
- ▲ λ increases / k decreases / g_0 grows: frequency decreases and
 \hookrightarrow time evolution $\propto \exp(\pm \alpha t)$. (if $\alpha^2 = -\omega^2$)
Exponentially unstable.

- \rightarrow Gravitational collapse for wave numbers

$$k^2 < k_J^2 \equiv \frac{4\pi G \rho_0}{c_s^2}$$

▼ k_J = Jeans wave number

$$\nabla \lambda_J = \text{Jeans wavelength} = \frac{2\pi}{k_J} = \left(\frac{\pi c_s^2}{G \rho_0} \right)^{1/2}$$

$$\nabla M_J = \text{Jeans mass} = \frac{4\pi}{3} \rho_0 \left(\frac{\lambda_J}{2} \right)^3 = \frac{\pi}{6} \rho_0 \left(\frac{\pi c_s^2}{G \rho_0} \right)^{3/2}$$

for a spherical perturbation with $\phi = \lambda_J$

$$\hookrightarrow M_J = \frac{\pi^{5/2}}{6} \left(\frac{R}{G} \right)^{3/2} \rho_0^{-1/2} T^{3/2}$$

$$= \frac{\pi^{5/2}}{6} G^{-3/2} \cdot \rho_0^{-1/2} c_s^3$$

$c_s^2 = RT$

- Energy of sound wave $E_{\text{sound}} > 0$, $\overset{\text{gravitational}}{\text{Energy}} < 0$

\hookrightarrow Instability sets in, when net energy is negative, i.e. when λ exceeds λ_J .

Bonnor-Ebert spheres



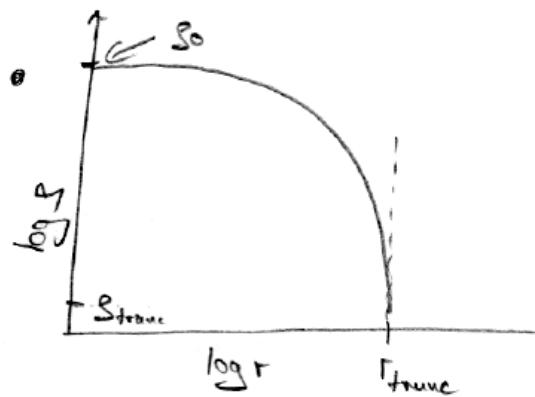
④ Isothermal equilibria of (pressure bounded) self-grav. spheres

- force balance \rightarrow static eqn $\rightarrow \boxed{\vec{\nabla} p = -g \vec{\nabla} \Phi}$
- ideal gas: $p = c_s^2 \rho$ with isothermal sound speed $c_s^2 = \frac{R}{\mu} T$

- spherical symmetry: eqn. of motion $\frac{c_s^2}{\rho} \frac{dp}{dr} = - \frac{d\Phi}{dr}$
- \hookrightarrow integration $\rightarrow \boxed{\rho = \rho_0 \exp(-\Phi/c_s^2)}$ hydrostatic eqn.

- include Poisson's eqn: $\boxed{\frac{1}{r^2} \frac{d}{dr} (r^2 \frac{d\Phi}{dr}) = 4\pi G \rho = 4\pi G \rho_0 \exp(-\Phi/c_s^2)}$ Lane-Emden equation

- regular eqn's from $\Phi=0$ & $\frac{d\Phi}{dr} = 0$ at $r=0$



if $\frac{\rho_0}{\rho_{\text{trunc}}} > 14$ only unstable
equilibria possible!

- Singular isothermal sphere if $\frac{\rho}{\rho_{\text{core}}} \rightarrow \infty$
 (or equivalently, if outer edge $r_{\text{core}} \rightarrow \infty$; or $\rho_{\text{ext}} \rightarrow 0$)

↳ SIS: $\xi = \frac{c_s^2}{4\pi G r} \quad \& \quad \frac{d\phi}{dr} = \frac{2c_s^2}{r}$

Shu (1979) assumes $\xi \leq 1$; but to reach SIS,
 system evolves through a sequence of unstable equilibria
 ↳ collapse sets in much earlier \rightarrow SIS with $v=0$
 will never be reached.

- solving *): define $\xi = \frac{r}{c_s} \sqrt{\frac{4\pi G \rho_0}{r}}$ ρ_0 = core density

↳ $\frac{d}{d\xi} \left(\xi^2 \frac{d\psi}{d\xi} \right) = \xi^2 e^{-4\psi}$ *)
 $\psi = \ln \frac{\rho}{\rho_0}$

sin of γ) with $\gamma(0) = 0$ & $\frac{d\gamma(0)}{d\xi} = 0$ curve finite at the center $\xi = 0$.

→ further change of variables:

$$y_1 = \xi^2 \frac{d\gamma}{d\xi}$$

$$y_2 = \gamma$$

→ coupled set of 1. order ODE's:

$$\frac{dy_1}{d\xi} = \frac{y_0}{\xi^2}$$

$$\frac{dy_0}{d\xi} = \xi^2 \exp(-y_1)$$

boundary conditions $y_0(0) = 0$ & $y_1(0) = 0$.

↪ ∃ family of solutions characterized by parameter

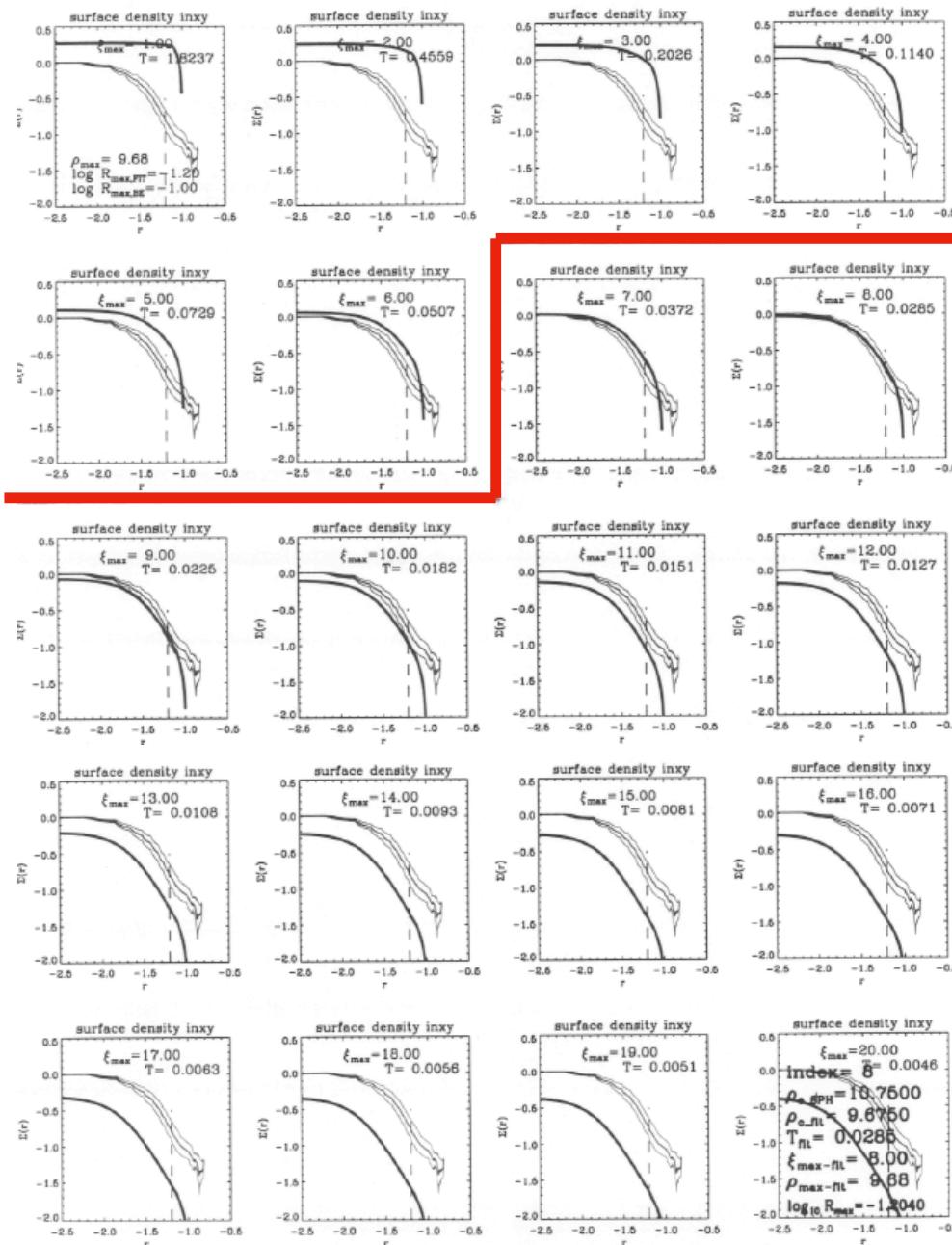
$$\xi_{\max} = \frac{r_{\text{trunc}}}{c_s} \sqrt{4\pi G \rho_0}$$

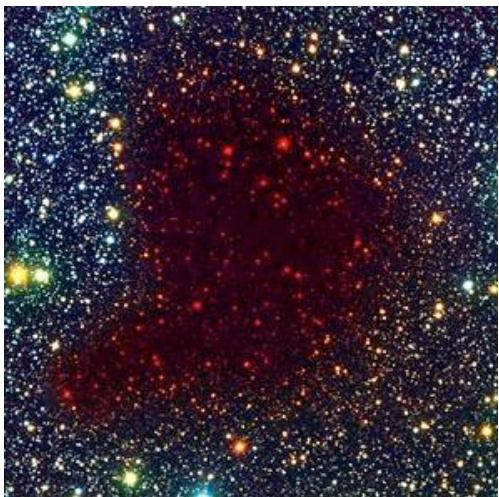
ξ_{\max} = value of ξ at outer boundary r_{trunc}

$\xi_{\max} > 6,5$ unstable equilibria: collapse

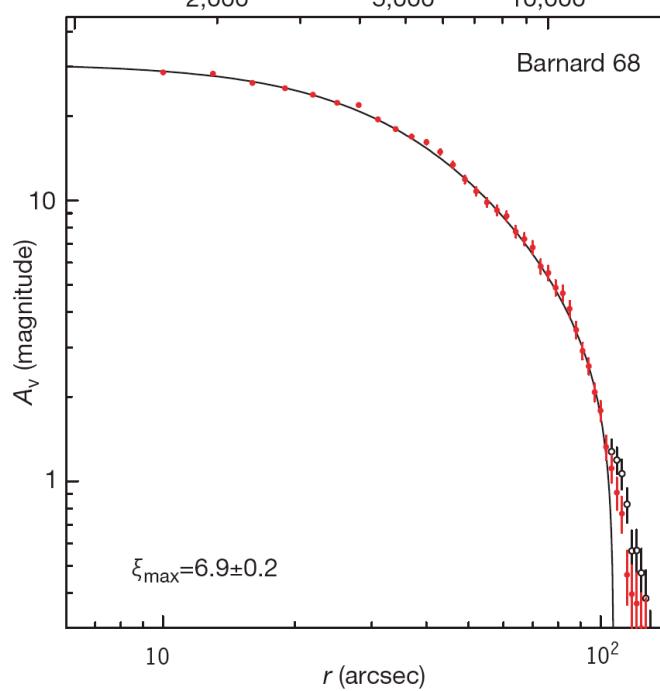
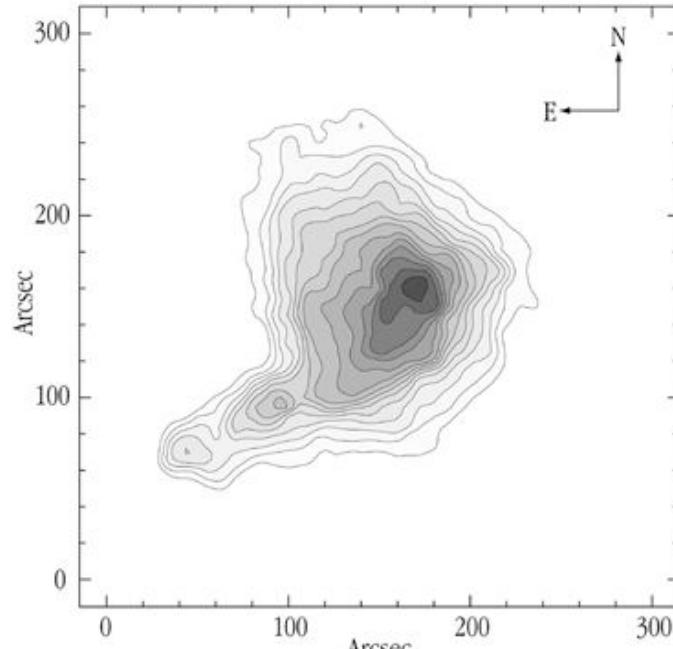
$\xi_{\max} < 6,5$ stable s.f.

stable
unstable

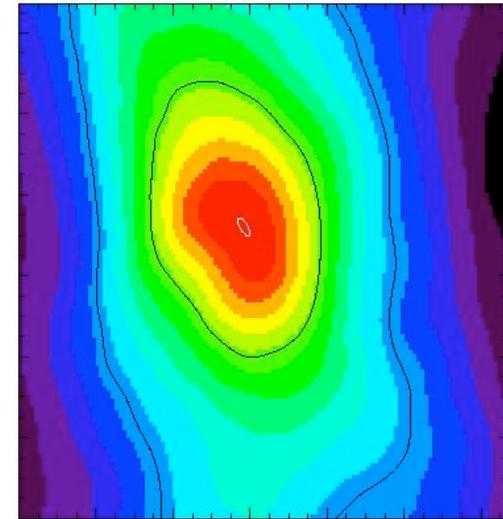
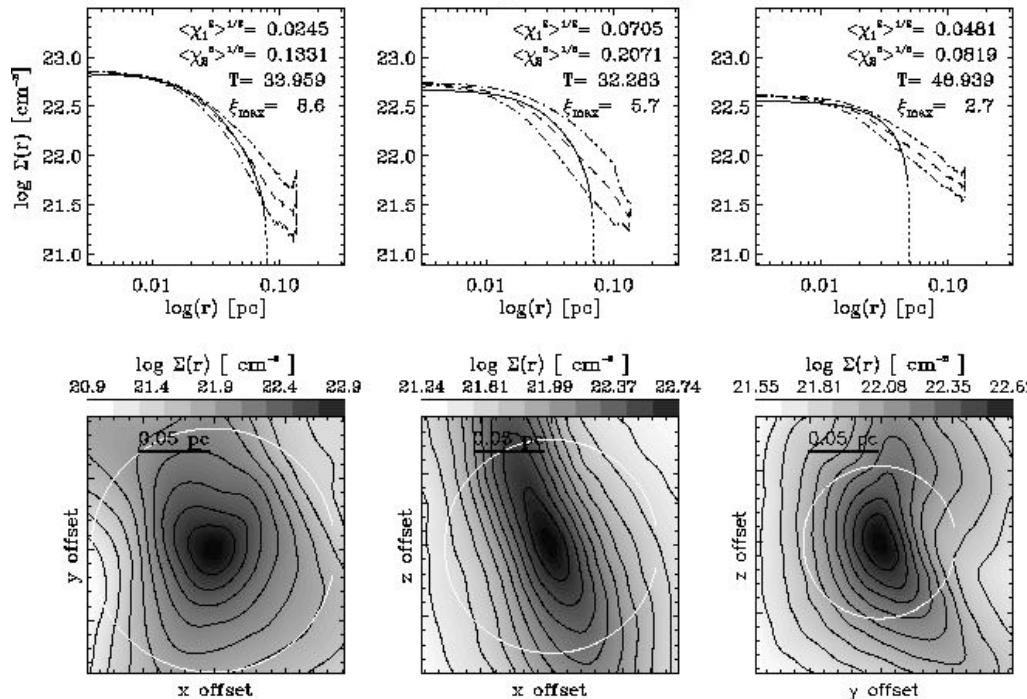




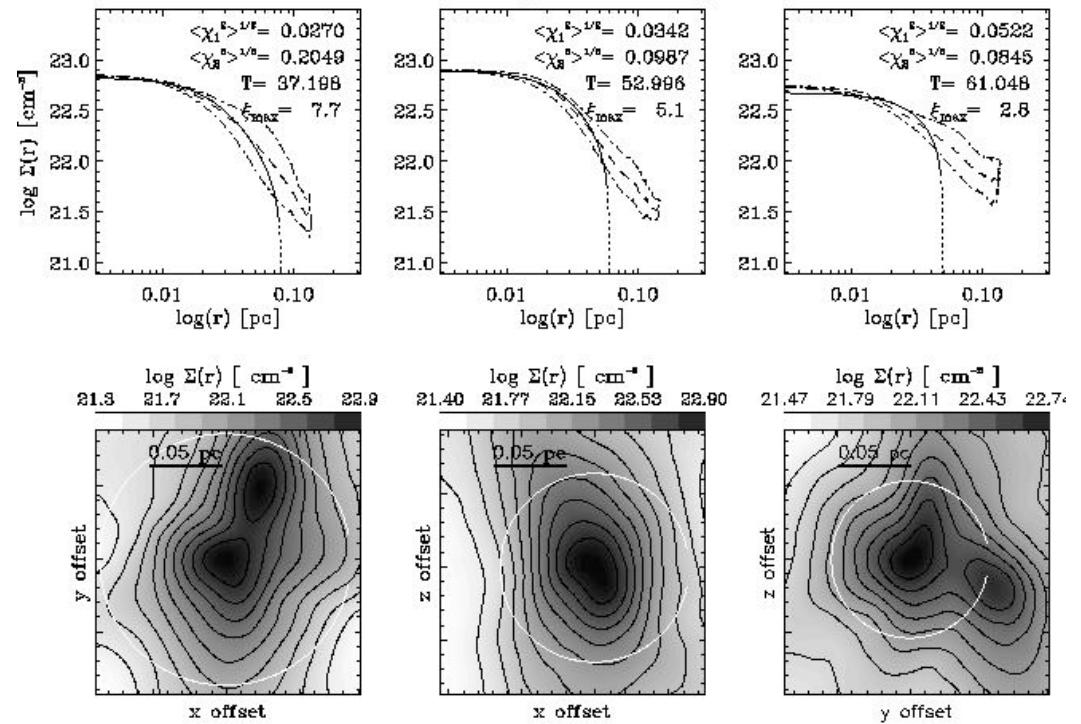
Alves, Lada, Lada (2001)



GC clump 26 time t_1



GC clump 04 time t_0



recommended literature



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